

TIM

Traceable in process measurement
EMRP project IND 62

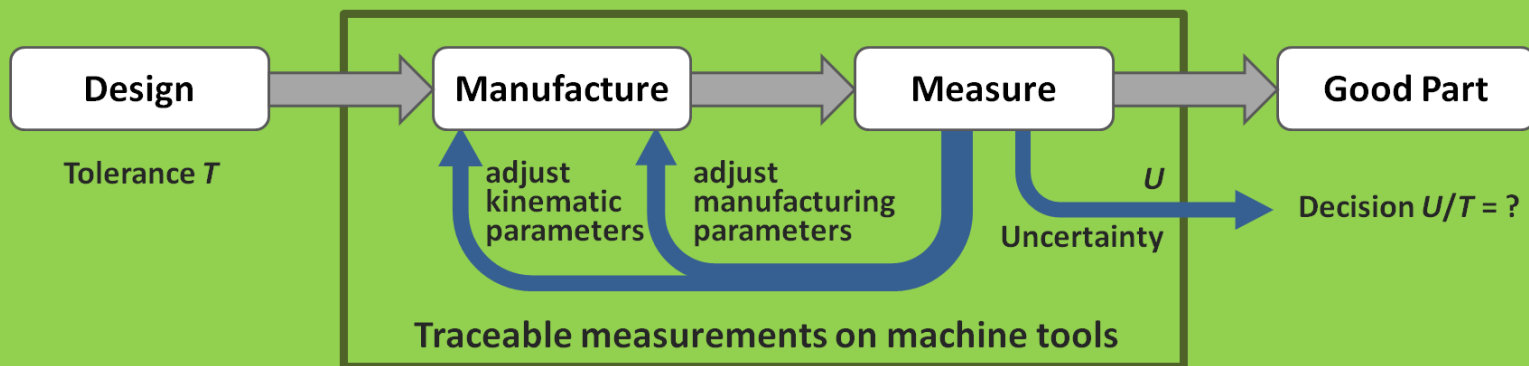
Metrology for machine tools: Needs and Expectations

Michael McCarthy 
National Physical Laboratory

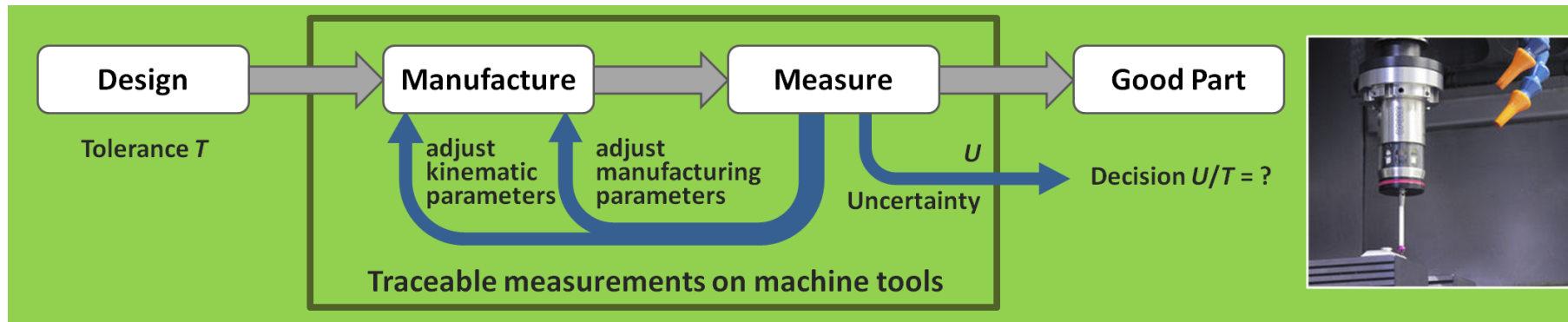


on behalf of Dr.-Ing. Klaus Wendt (PTB) (TIM project coordinator)

Traceable measurement process Concepts for Integration in Machine Tools



Traceable in-process dimensional measurement
(IND 62 TIM)



8 Funded Partners



8 Unfunded Partners



2 REG Partners



The JRP comprises of seven work-packages, these include:

1) Framework

- Review of standards and in-process metrology
- Basic guideline describing traceability routes, acceptance and fit-for-purpose tests

2) Robust measurement standards

- Specification, design and manufacturing of 6 material standards
- Robust against environmental influences and mechanical stress
- With or without large form deviations

3) Mobile simulation chamber

- Manufacturing of a chamber for simulating the manufacturing and machine tool environmental conditions (e.g. temperature, humidity, air circulation, etc.)

The JRP comprises of seven work-packages, these include:

4) Procedures for ensuring reliable measurements on machine tools

- Determination of the **performance** and **task-specific measurement uncertainty** of machine tools using material artifacts with low / high CTE, little / large form errors

5) Demonstration and integration focused on end-user needs

6) Creating Impact

- Dissemination and transfer of the outputs of this JRP to the European machine tool, manufacturing and metrological community

***Paper, Industrial interaction, Conferences,
Workshops***

Manufactured parts are normally measured immediately after machining on the machine tool

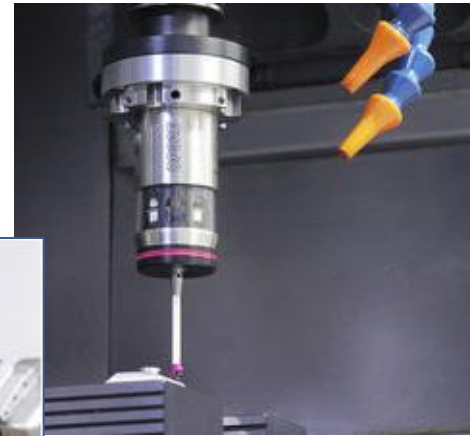
- *by a tactile probing system attached to the tool holder*
- *And possibly separate optical 3D measuring system*

or in-process

- *Using optical measuring sensors*

‘on-machine’ measurements form the basis for a definite decision, whether or not the manufactured parts lie *within the specified tolerance*

go/no-go decision is based on *reliable and traceable measurement uncertainties*



TIM is aiming at:

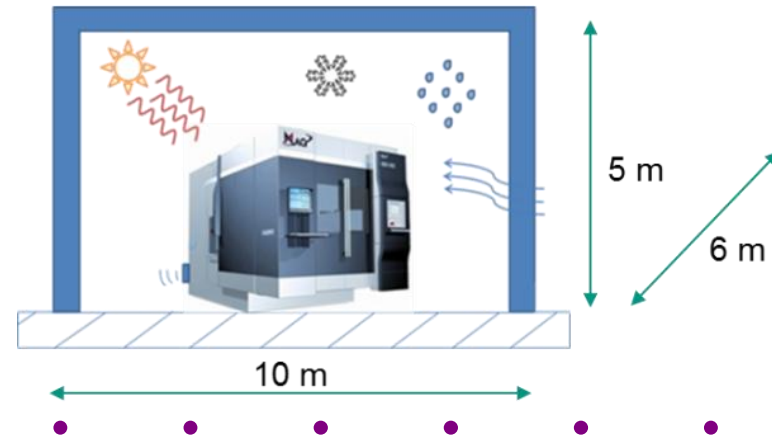
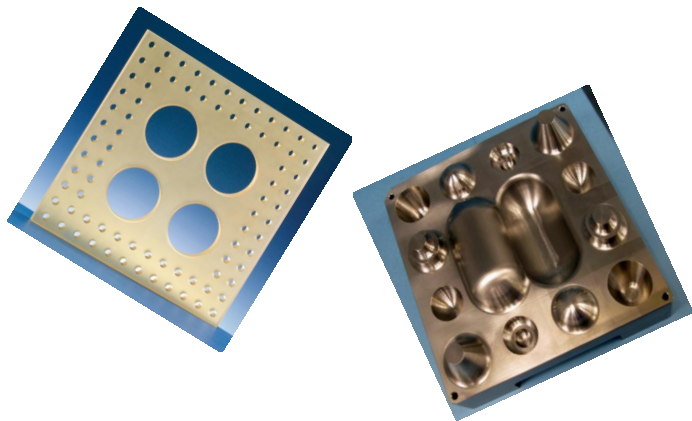
- **Evaluating** the dimensional metrology **capability of CNC** metal cutting machine-tools such as ~ milling, drilling and grinding machines

Using various methods and procedures

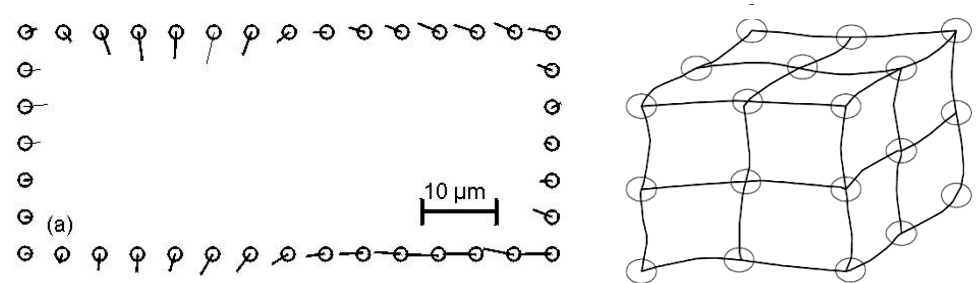
- To demonstrate the *general measurement capability by comparison* with calibrated reference artefacts (test lengths)
- And to determine **specific uncertainties** for measuring and inspection tasks
- *To demonstrate effectivity, using practical tests and show the benefits*
 - **To end users** and machine tool manufactures
 - Through real measurements of **standards and calibrated workpieces**
 - And under **shop floor conditions**

TIM is aiming at

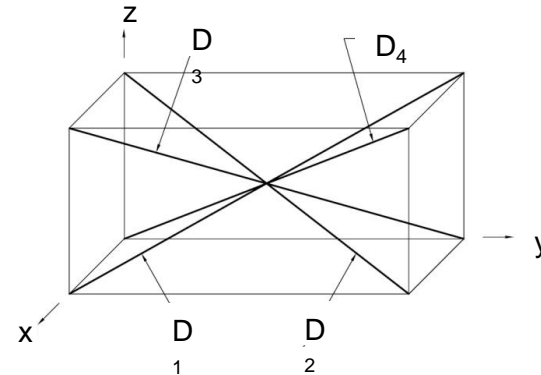
- **Improving the measuring capability** of CNC metal cutting machine tool through *correction of geometric and thermally induced distortions* of the machine by:
 - **Volumetric error mapping** using general applicable material standards or other techniques such as laser interferometry where required.
 - **Task-specific error** mapping using material standards with multiple features.
 - Using a **climate chamber** for simulating varying environmental conditions.



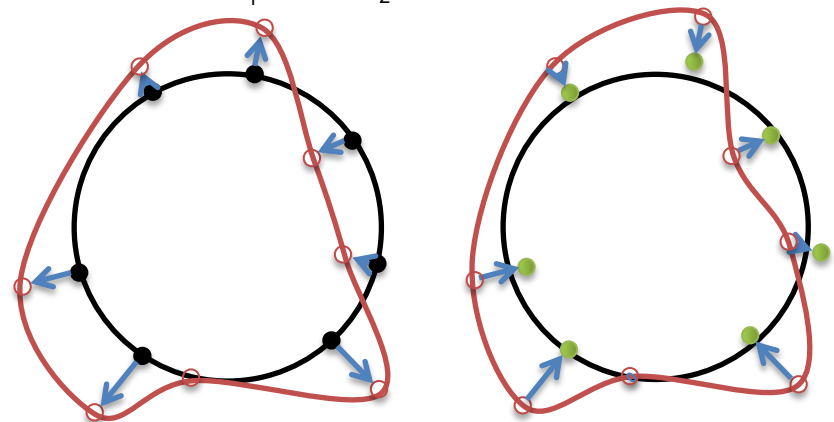
- Volumetric error mapping**
 Mapping of geometric errors across the entire working volume (generally *requires* a mathematical error model)



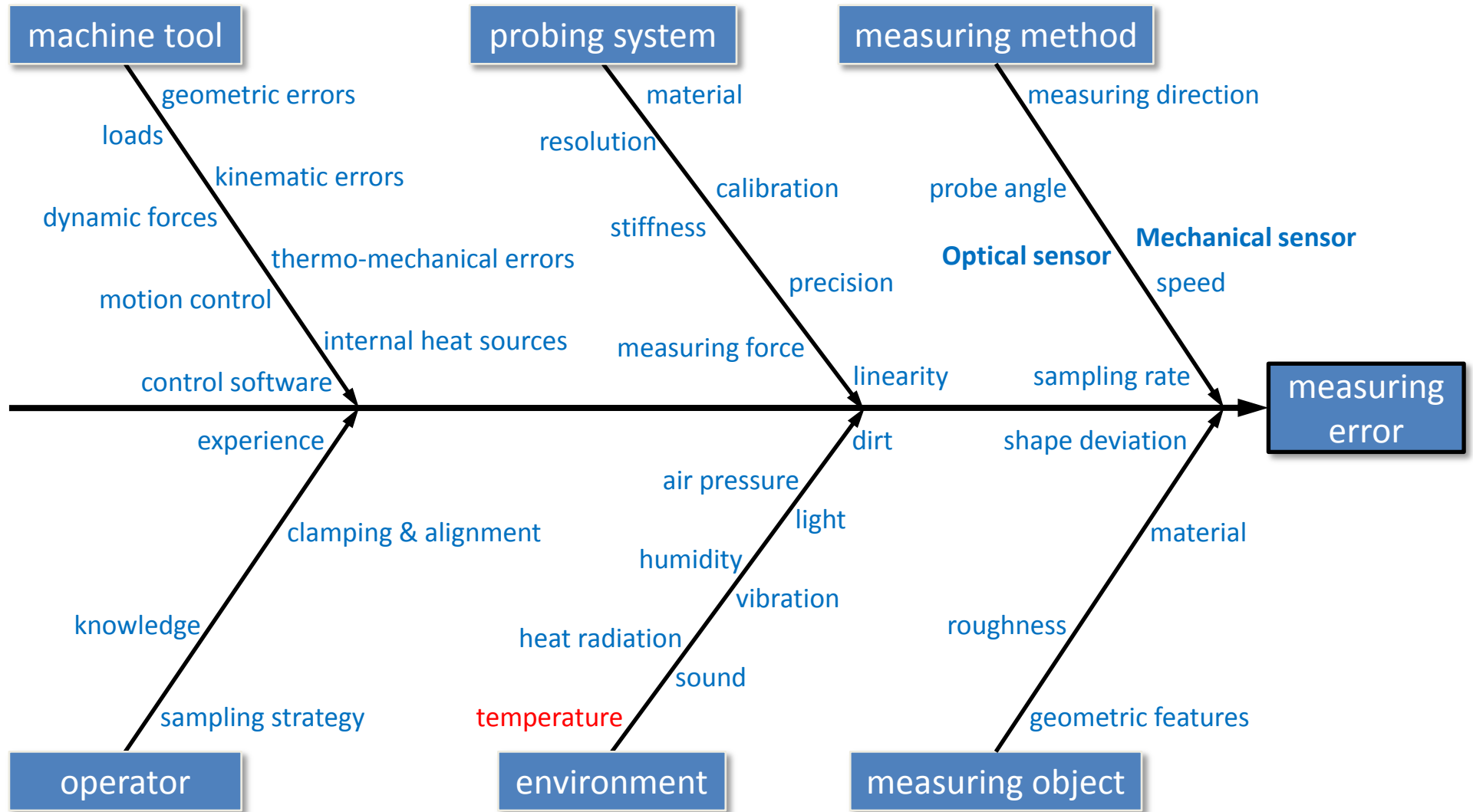
- Verification of MPE**
 Verification of error compensation and MPE compliance test



- Task-specific error mapping and correction**
 Determination of size, form and position errors of geometric features (generally *does not require* a mathematical error model)

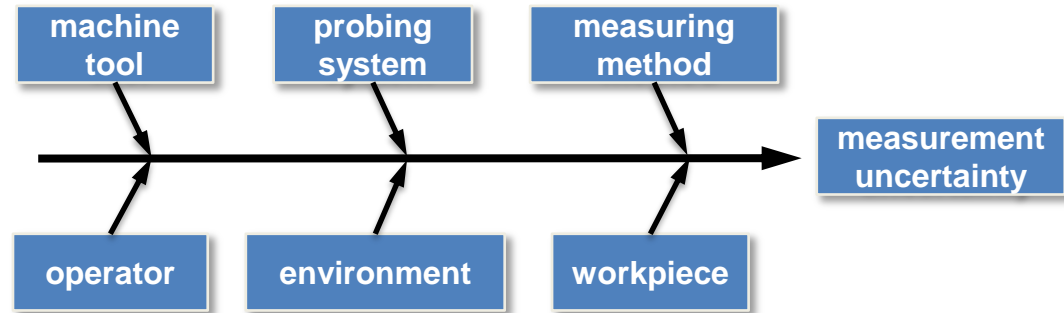


Sources of measuring errors



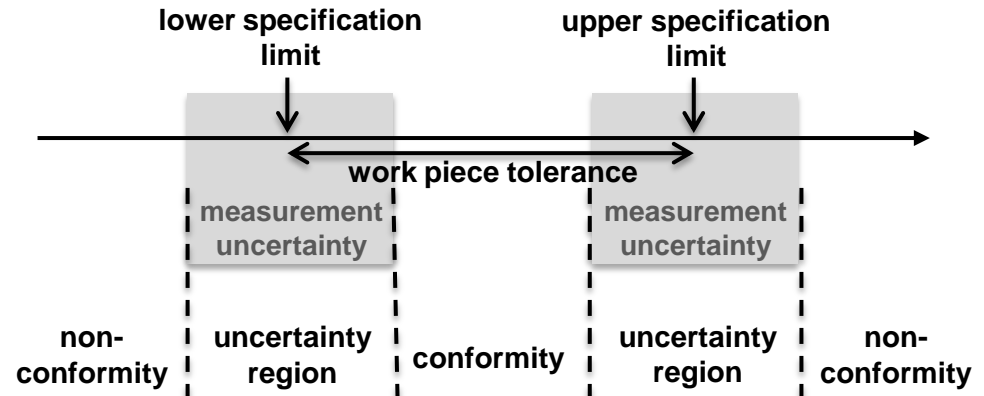
- Task-specific measurement uncertainty**

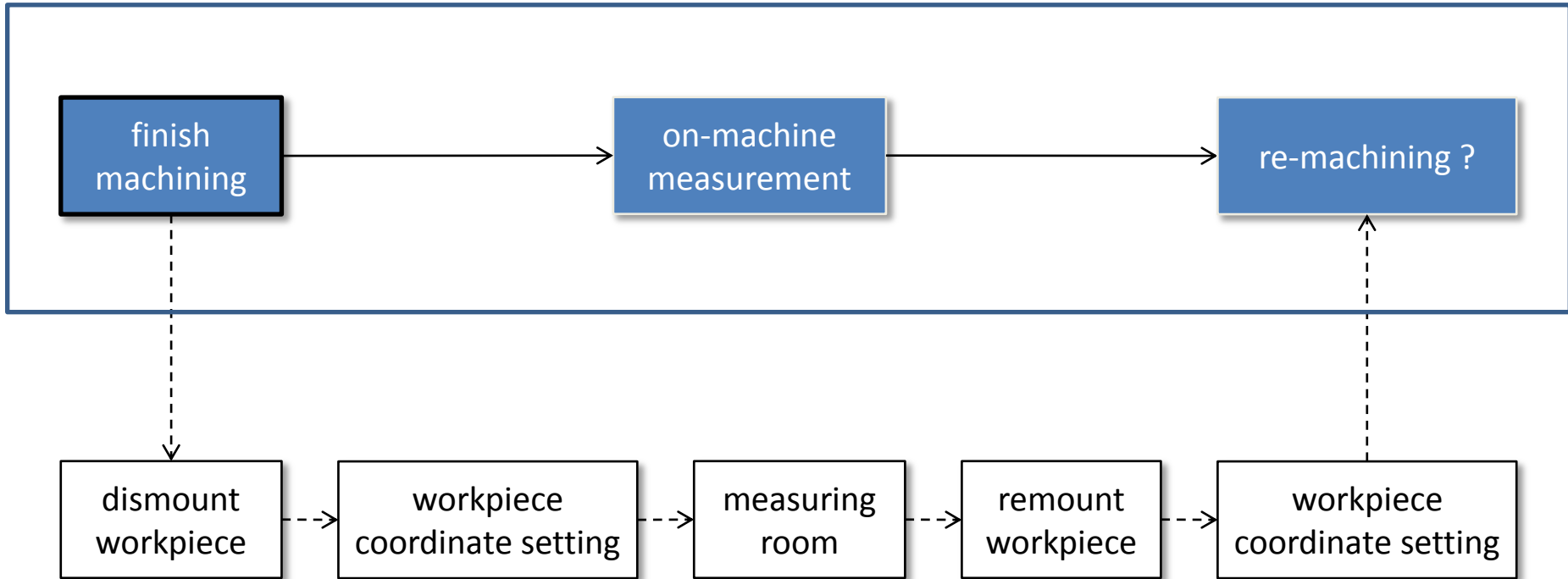
Determination of measurement uncertainty for shape and form measurements / typical geometric features



- Fitness-for-purpose**

Assessment of the capability of a machine tool to measure geometric features with sufficient small accuracy compared to the permissible manufacturing tolerance

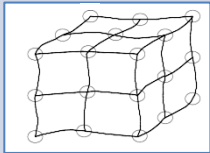
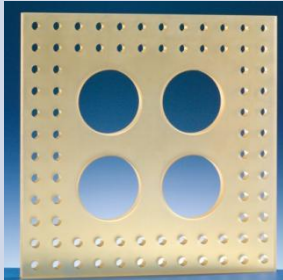
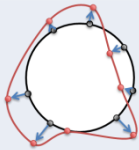
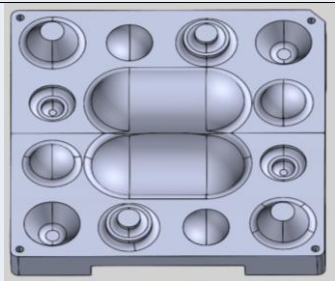
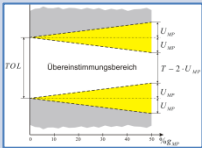



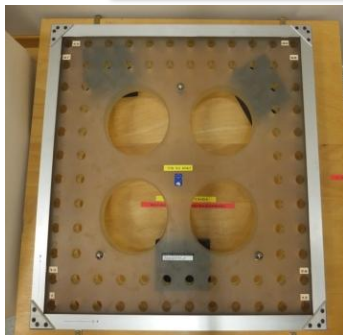


Benefit: Shortened measurement duration
reduction of energy costs (no expensive air-conditioning)

Challenge: Measurement under shop floor conditions
complex determination of measurement uncertainty

Target accuracy: 5 $\mu\text{m}/\text{m}$

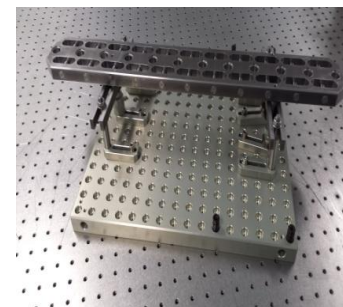
procedure	material standards	error sources
<p>Volumetric error mapping verification of MPE</p> 		<p>geometric, thermo-mechanical</p>
<p>Task-specific error mapping task-specific measurement uncertainty</p> 		<p>+ dynamic forces + motion control + control software</p>
<p>Fitness-of-purpose</p> 	 <p>Source: eumetron</p>	<p>++ loads ++ heat</p>



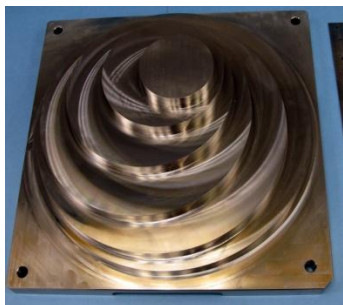
PTB: Hole plate



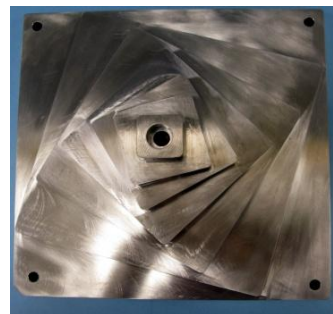
UM: Ball bar



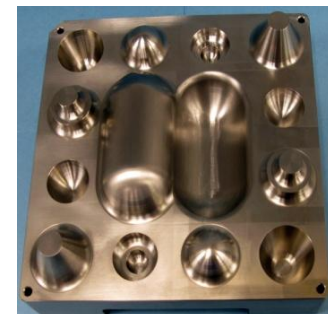
LNE: Hole bar



NPL: Eccentric cylinders



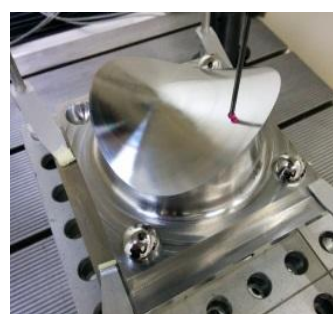
NPL: Rotating squares



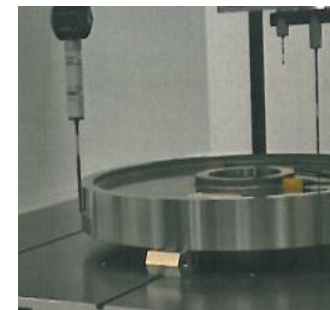
NPL: Prismatic geometries



PTB: Multi-feature check



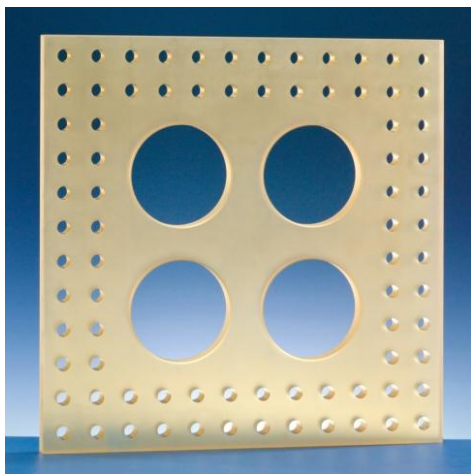
CMI: Hyperbolic paraboloid



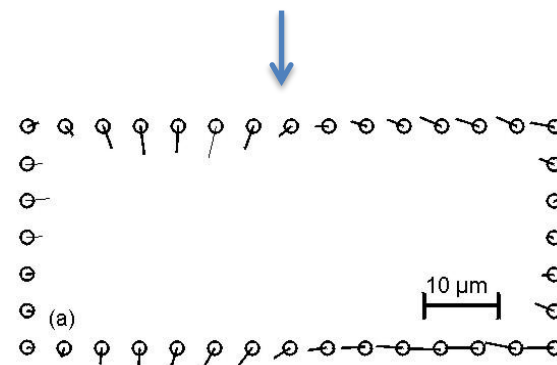
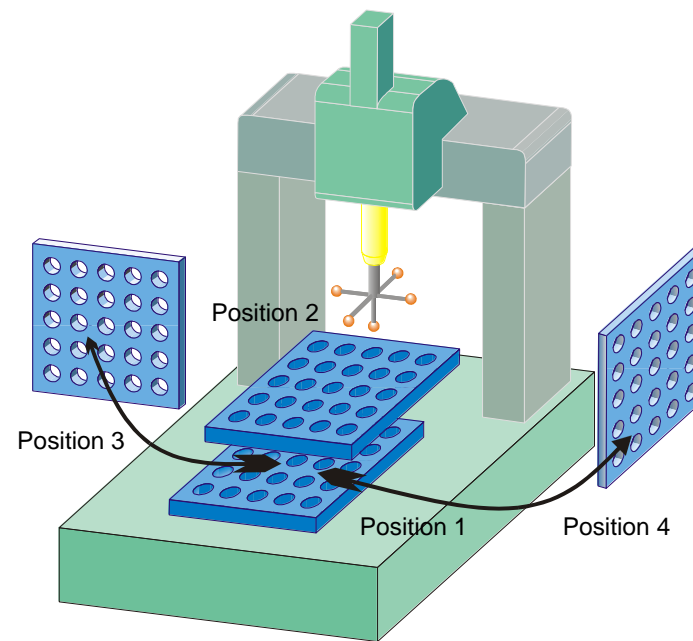
VTT: 3x Roundness Disks

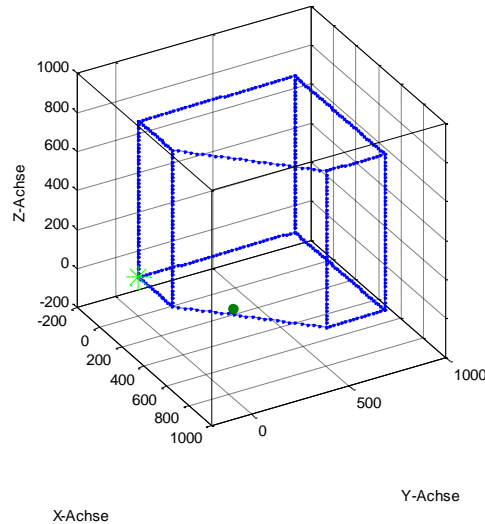
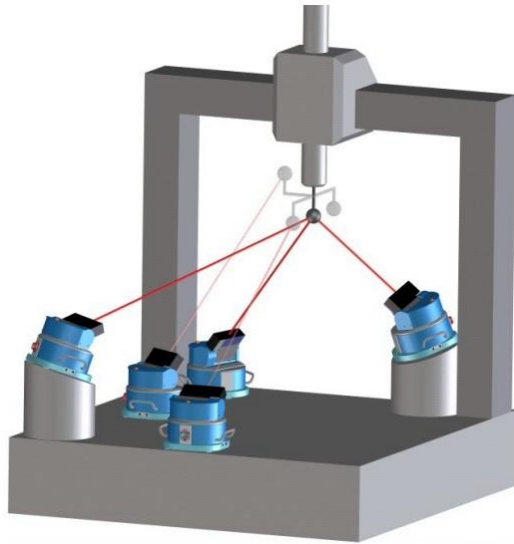
Linear axes:

- *Uncorrected machine tool*
mapping of systematic machine errors based on measurements of a thermo-invariant reference artefact in four or more positions
- *Corrected machine tool*
mapping of remaining machine errors for determining the achievable accuracy



PTB: Hole plate

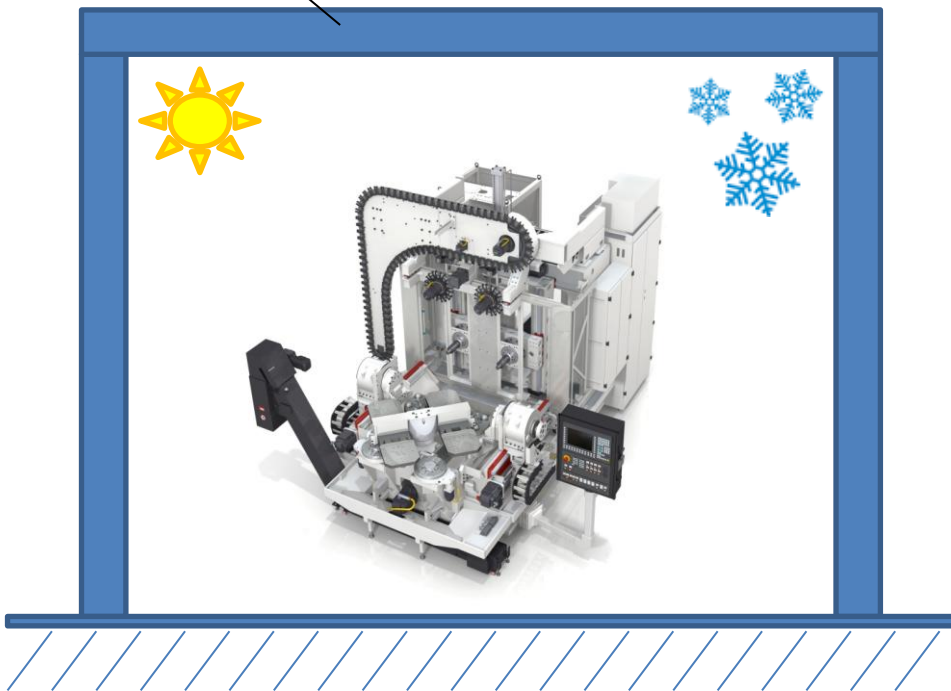




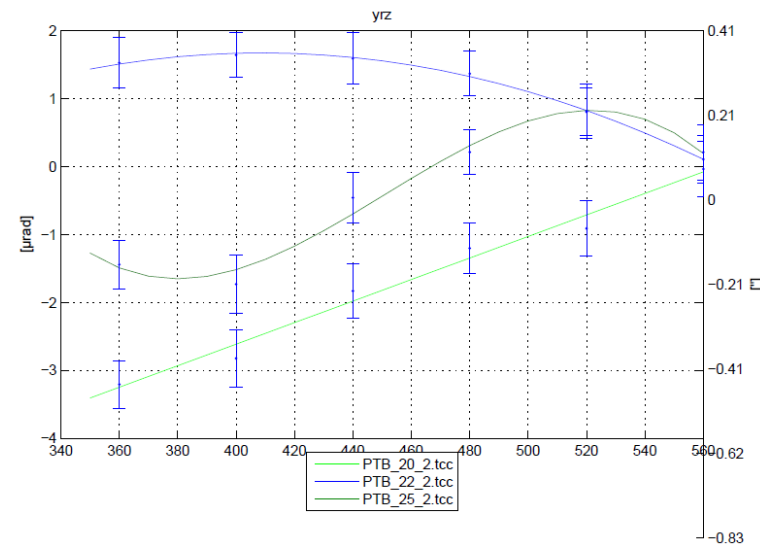
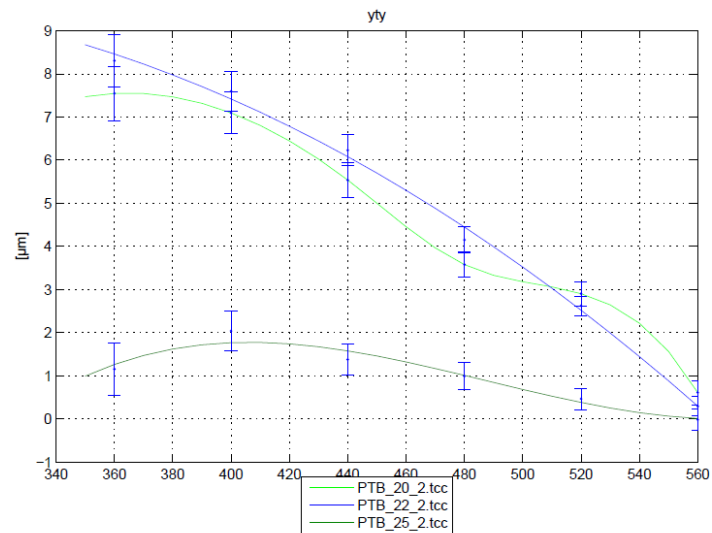
```
G01 G90 X800.0000
Y0.0000 Z0.0000
// (Point 1 of 929)
G04 X1.0
G01 G90 X780.0000
Y0.0000 Z0.0000
// (Point 2 of 929)
G04 X1.0
G01 G90 X760.0000
Y0.0000 Z0.0000
// (Point 3 of 929)
G04 X1.0
G01 G90 X740.0000
Y0.0000 Z0.0000
// (Point 4 of 929)
G04 X1.0
...
```

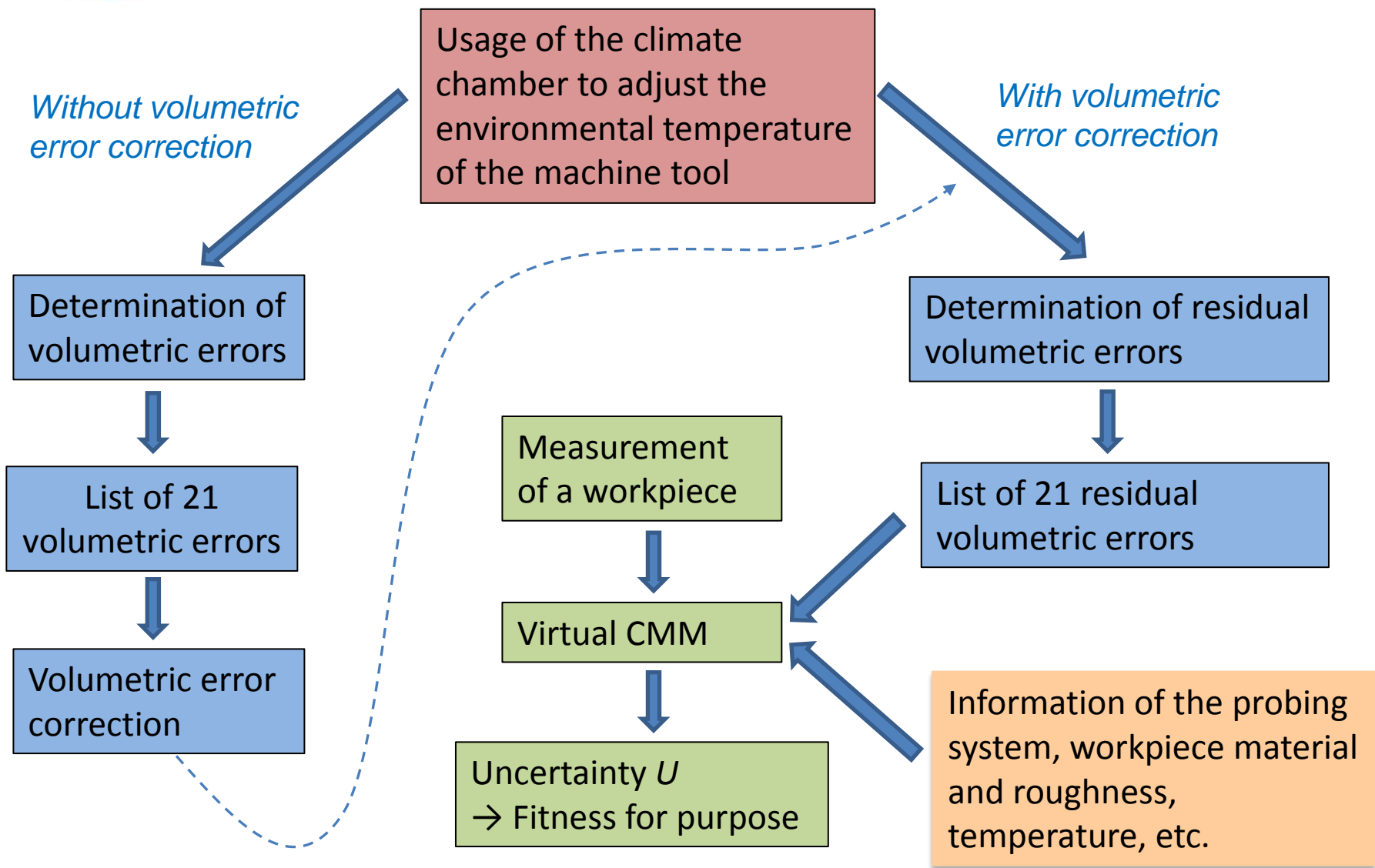
- Determination of volumetric errors via **multilateration** with the help, for example using **self-tracking laser interferometers** each in conjunction with a special **gimbal type reference optics**.
- Suitable for **both linear and rotational axes**
- Such a system could **generates CNC code** for the machine tool
- And in principle could **generate a correction table** for a machine tool controller.

Climate chamber

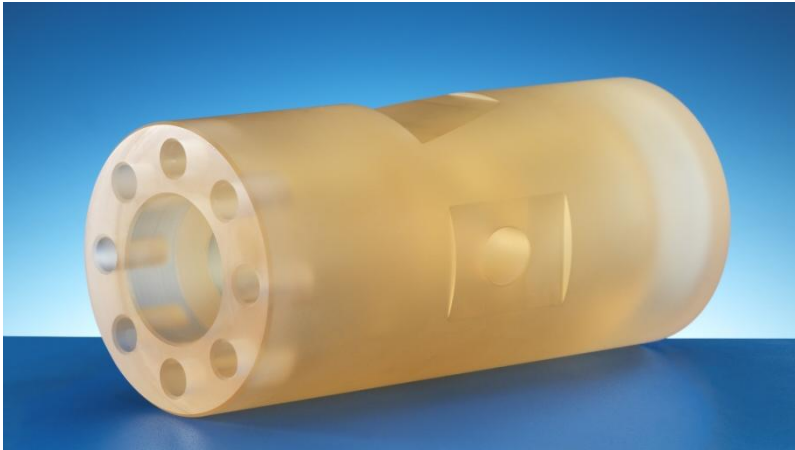


Determination of volumetric errors at different temperatures:
 $T = 15^{\circ}\text{C}, 20^{\circ}\text{C}, \dots, 35^{\circ}\text{C}$



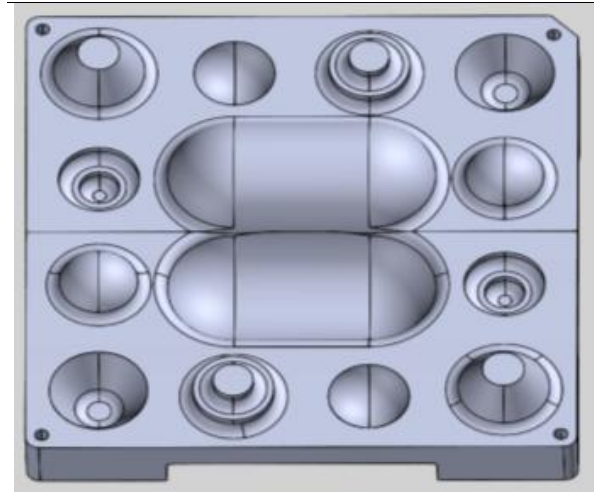


Traceability for tactile measurements (PTB)

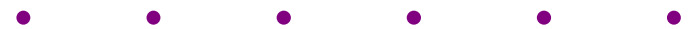


- close to zero thermal expansion (made from Zerodur®)
- specifications:
 - form errors $< 1 \mu\text{m}$
 - roughness $< 0.2 \mu\text{m}$
 - position and size of features will be calibrated on CMM
- measurement tasks:
 - hole
 - flat surface
 - coaxially

Traceability for optical measurements (NPL)



- Prismatic artefact
- Extremely low coefficient of thermal expansion (made from Invar)
- specifications:
 - plated surface
 - form errors $< 5 \mu\text{m}$
 - position and size of features will be calibrated on CMM, accuracy $\sim 2 \mu\text{m}$

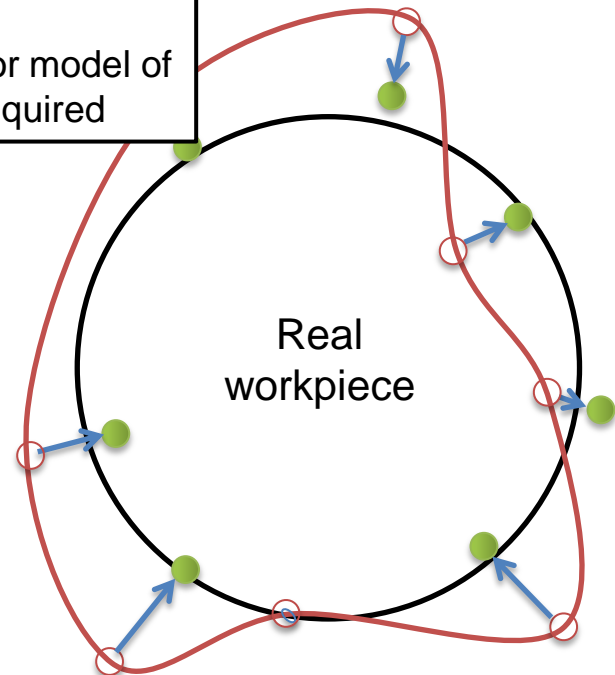
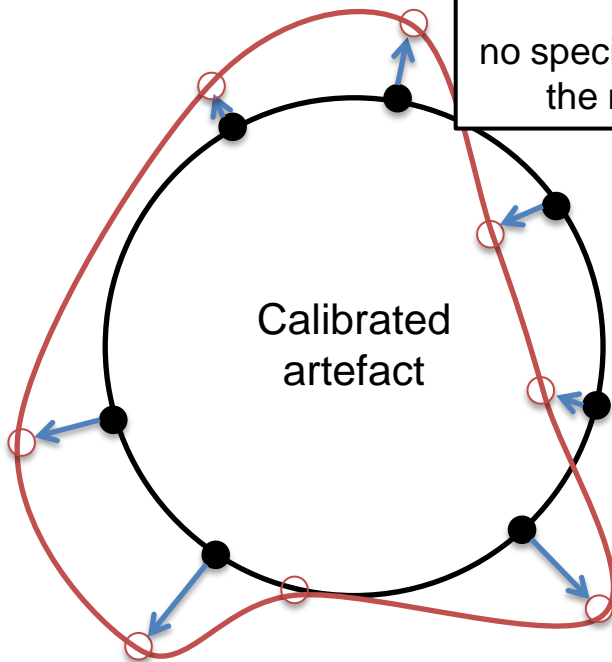


Approach:

- acquire local error vectors by measuring a calibrated artefact (e.g. Zerodur® Multi-Feature-Check, Prismatic artefact or a workpiece replica)

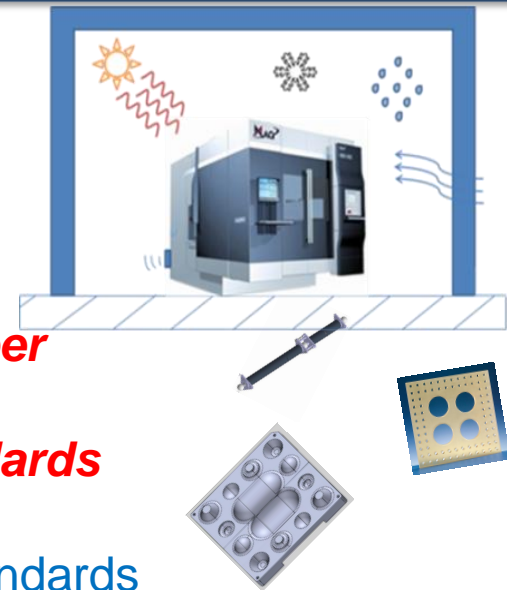
- measure real workpiece using tactile or optical probe
- use the local error vector to correct the points measured point by point
- evaluation of the **corrected points**

Advantage
no specific geometric error model of the machine tool is required



Final outcome of the TIM project

- Provision of portable **environmental simulation chamber**
- various high accurate, **thermo-invariant material standards**
- **Industrial trails** using Machine tool in Chamber with standards
- **Five Good Practice Guides** for
 1. Checking the **overall measurement performance**
 2. **Assessing the fitness-for-purpose** of on-machine measurements
 3. Verification of **area-scanning** metrology systems on machine tools
 4. **Mapping task-specific** measurement errors using **multi purpose material standards**
 5. Measuring roundness on roller machines and determining the associated uncertainty



Questions...?: