



sound pressure produced in a coupler by a piston.

its output voltage and the applied sound pressure.

$$M_P = \frac{U_m}{P_c}$$

coupler and the measurement of the volume velocity of the piston.

$$P_c = Z_T \int_S v_p ds$$
 If rigid piston $P_c = Z_T j \omega S$



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A laser pistonphone designed for absolute calibration of infrasound sensors from 10 mHz up to 20 Hz

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Equivalence of calibration are demonstrated through method comparisons: • High frequencies: LS1 microphone (reciprocity calibration) traceable to the SI (2 Hz – 20 Hz) • Low frequencies: Differential capacitance manometer (MKS Baratron Type 616A) traceable to

- the SI (DC)

Uncertainties: Example for a microphone B&K Type 4160

Frequency (Hz)	0.010	0.016	0.03	0.06	0.13	0.25	0.50	1 – 8	16	20
Amplitude:										
Expanded uncertainty	0.16	0.12	0.09	0.06	0.05	0.04	0.04	0.03	0.04	0.04
in dB (k=2)										
Phase: Expanded uncortainty	2.06	1 2 2	0.70	0 13	0 3 2	0.27	0.25	0.24	030	033
in degree (k=2)	2.00	1.20	0.70	0.43	0.52	0.27	0.25	0.24	0.30	0.55

