Metrology for Future Energy Transmission

WP4: METROLOGY FOR HVDC GRID CONDITION MONITORING

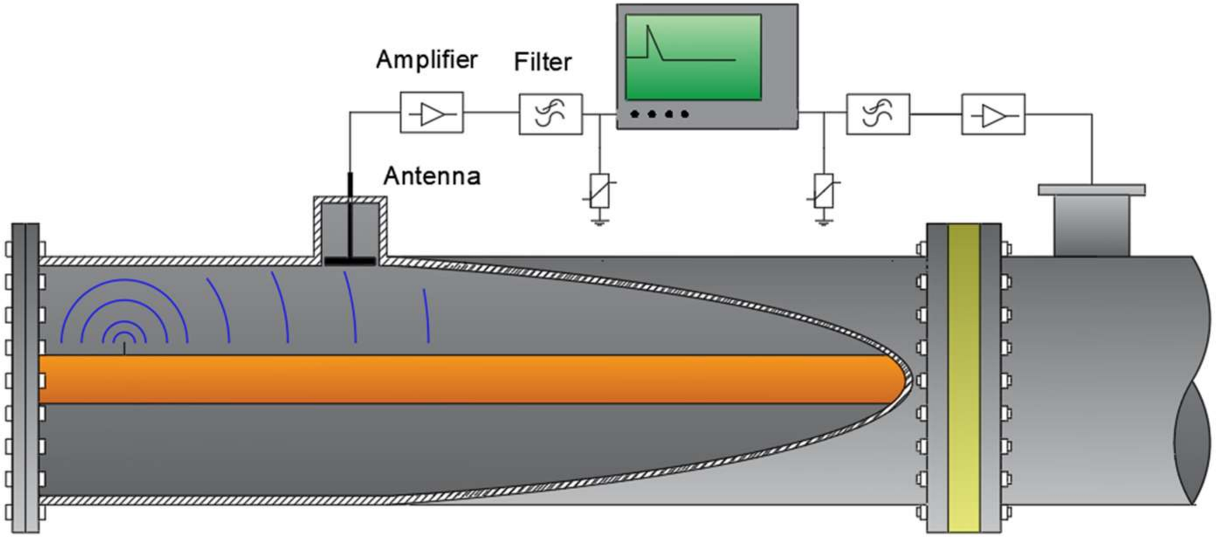
TASK 4.2: PROCEDURE FOR CHARGE EVALUATION IN HVDC GIS USING MAGNETIC SENSORS MEASURING IN THE 30 - 300 MHZ RANGE

The EMPIR initiative is co-funded by the European Union's Horizon 2020 research and innovation programme and the EMPIR Participating States

Project Overview

Motivations:
-The increased need for gas-insulated substations (GIS) with remote monitoring.
- The IEC 60270 method is difficult to apply for onsite online substations.
- Unconventional methods do not provide a calibrated measurement.

This research focuses on an unconventional method in the very-high frequency range, aiming to measure calibrated online PD in on-site substations.



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Content

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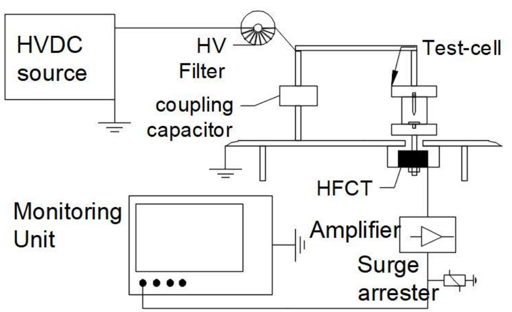
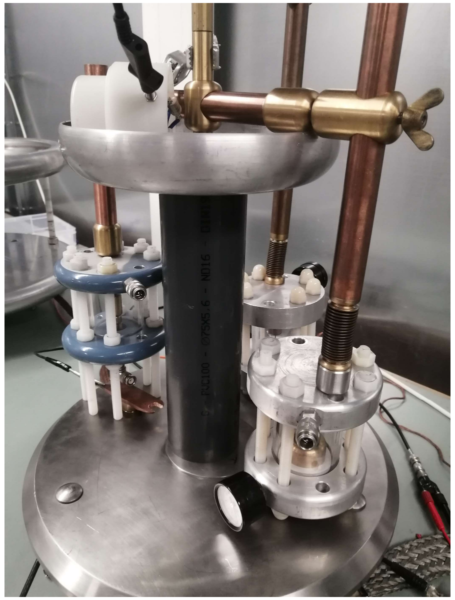
1. HVDC PD parameters

- The PD BW does not change after electric ageing for corona discharge, jumping particle, and Floating electrode. A change of BW was observed in SD. The PD BW determines the BW of the measuring system.
- Data set: PD amplitude, repetition rate, and pulse oscillography as a function of aging time.

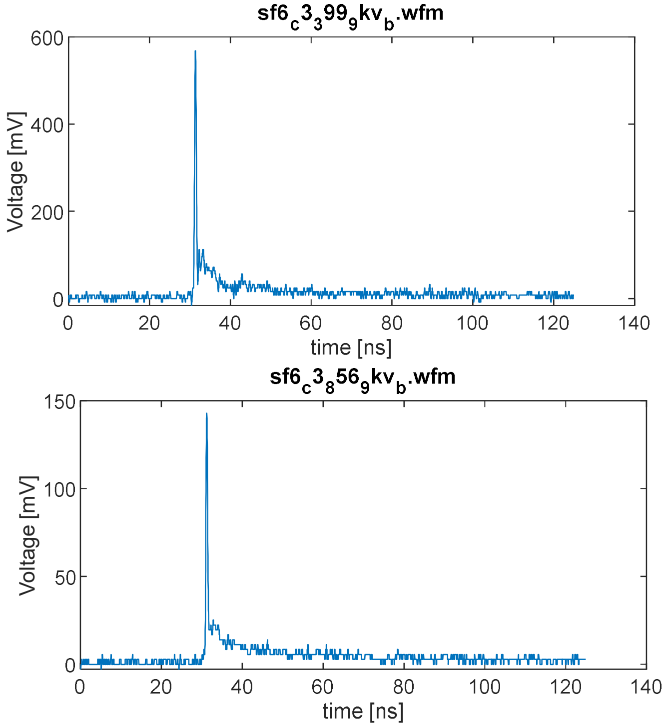


	Corona	FE	SD	JP
no ageing	>1000 MHz	>500 MHz	350 MHz	>500 MHz
end of ageing	>1000 MHz	>500 MHz	125 MHz	>500 MHz

Top: Test-setup for PD monitoring. Bottom: PD bandwidth before and after ageing.



Test-setup picture for PD monitoring.



Top: aged corona defect after 339 hours. Bottom: aged corona defect after 856 hours.

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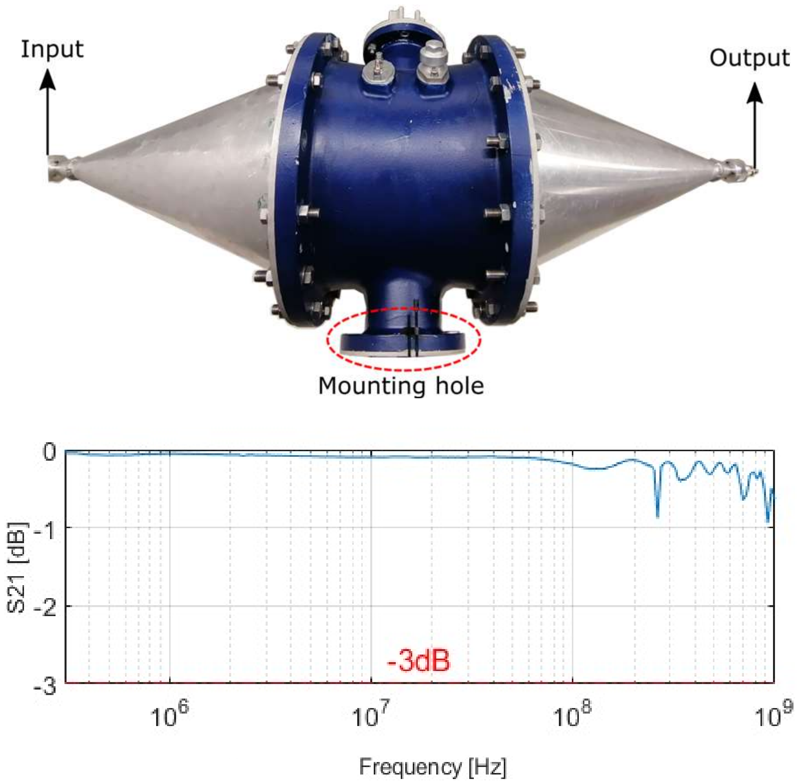
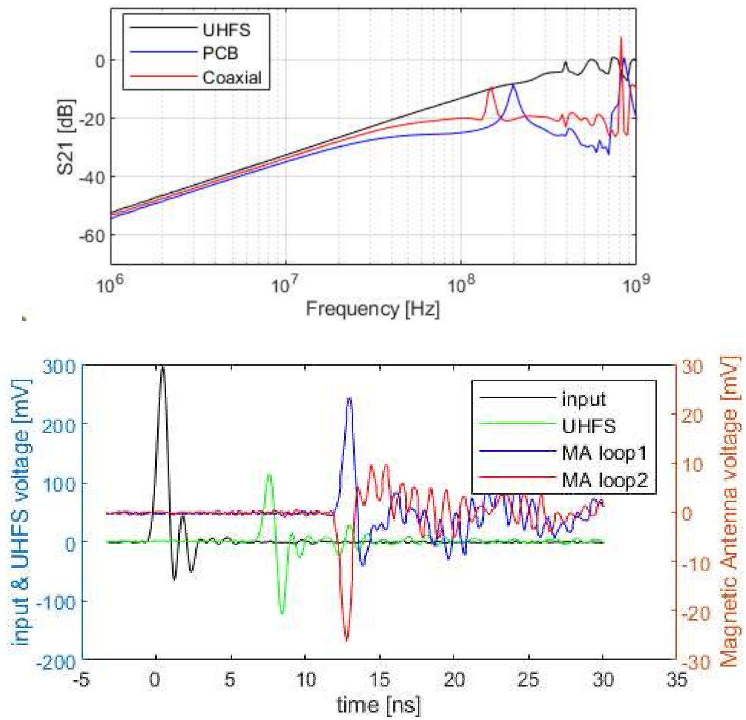
2. Test Workbench

- 1GHz bandwidth workbench for PD sensors characterization.



Top: Test bench picture. Bottom: Testbench frequency response.



Top: Bode diagram of different antennas. Bottom: Time domain measurements for different antennas.

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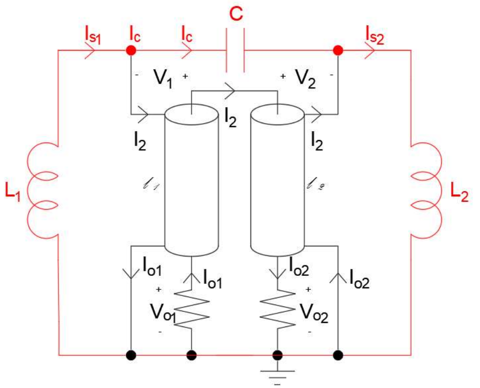
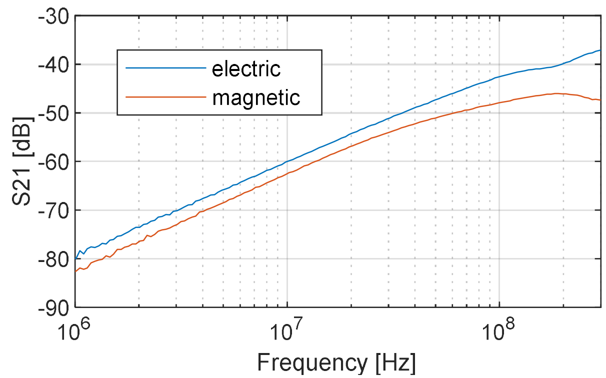
3.1. Sensor development

- Balanced magnetic antenna with a frequency range of up to 300MHz.
  - Higher common-mode noise rejection.
- Addition of 50 Hz electric field grading.
  - Aluminum and carbon black combination.
- Electric shield as an electric antenna.
  - Possibility to combine magnetic and electric field sensing.



Balanced Magnetic Antenna diagram.

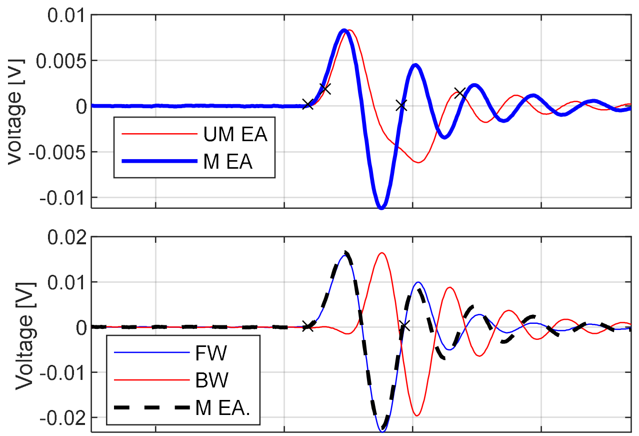
VHF sensor picture



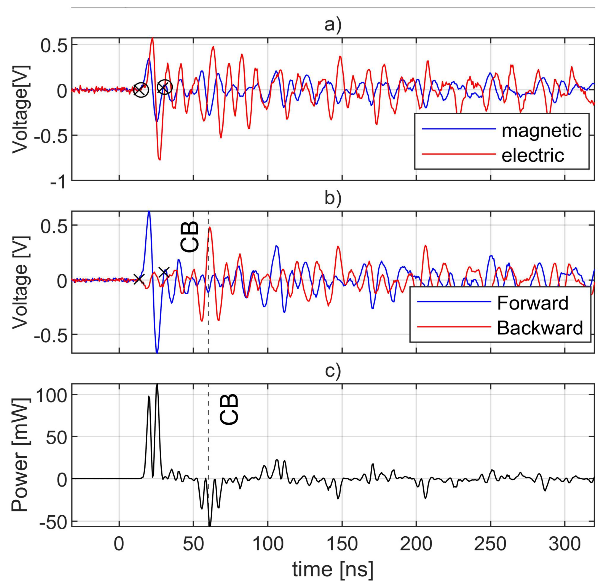
Frequency response of electric and magnetic antennas.

3.2. Sensor development

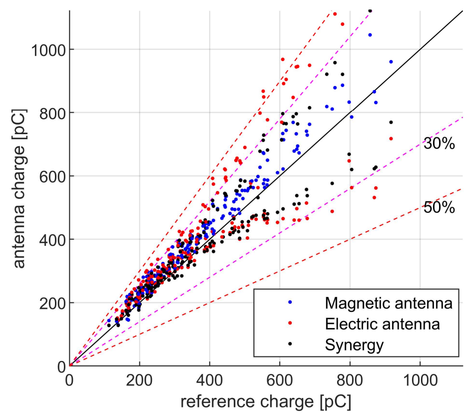
- Combination of VHF electric and magnetic sensor for PD power flow and reflection suppression for PD charge improvement.



Top: Overlapped pulse and matched pulse. Bottom: Forward and backward pulse and matched pulse.



PD measured with: a) magnetic and electric antenna, b) forward and backward pulses, c) power flow.



Antennas and synergy charges compared with reference charges for 200 PDs.

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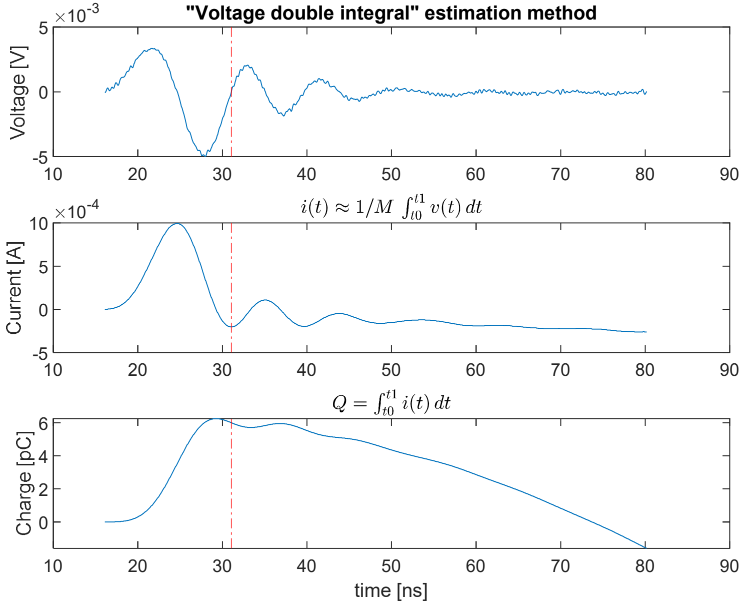
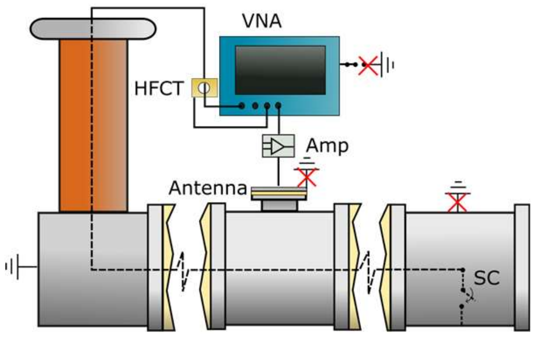
4. Charge Estimation procedure

- The voltage double integral method is based on the sensor's derivative response

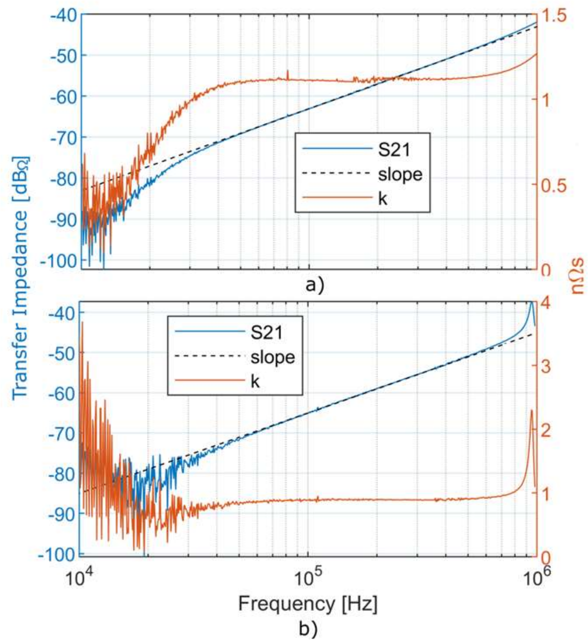
$$H(s) \approx \frac{sk}{s^2\omega_2{}^2 + s\omega_1 + 1} \qquad Q \approx \frac{\iint u(t)dt^2}{k} \qquad \left|\frac{dH(\omega)}{d\omega}\right|_{\omega\to 0} \approx k$$



Charge estimation development.



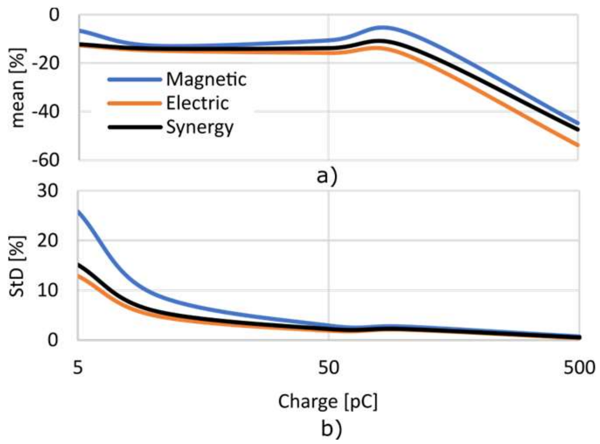
Calibration procedure.



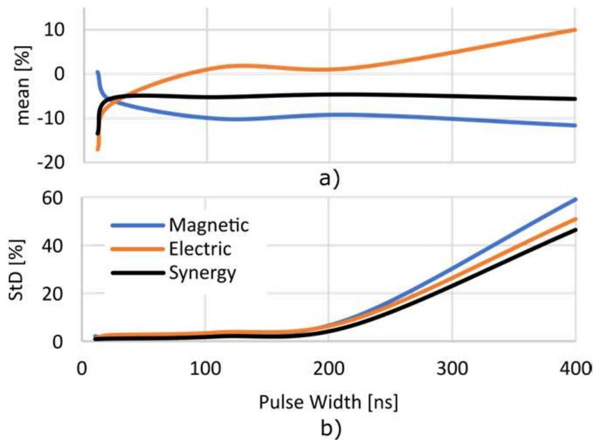
Calibration constant measurement for electric (top) and magnetic (bottom) antenna.

5.1 LV validation

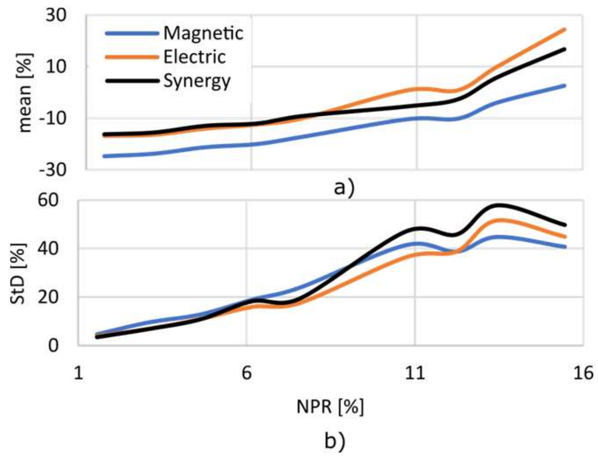
- Charge estimation uncertainty in the LV test bench.
  - Magnitude linearity
  - Frequency linearity
  - Noise to signal ratio



a) Mean and b) standard deviation error with different charge inputs.



a) Mean and b) standard deviation error with different pulse lengths inputs.



a) Mean and b) standard deviation error with different NSR inputs.

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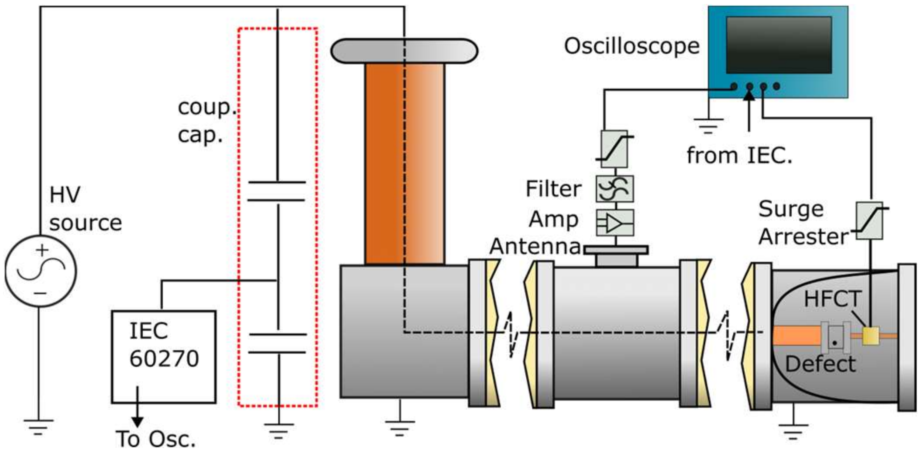
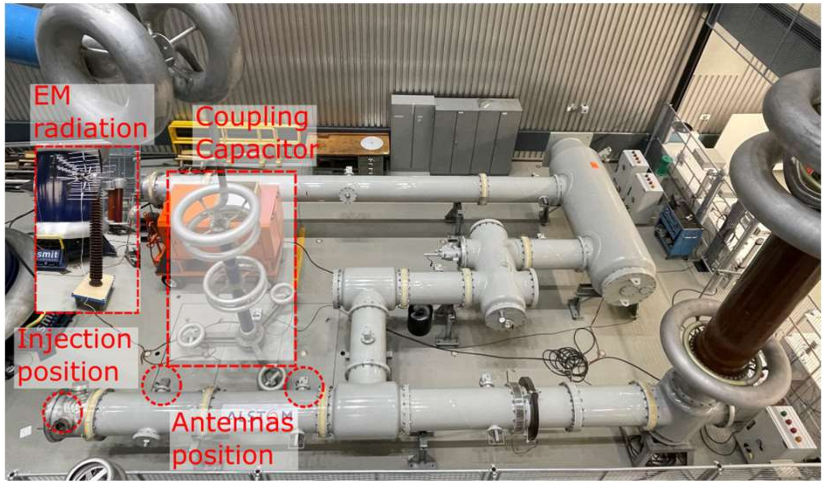
6.2.1 HV Validation

- HV test bench for characterization and validation of magnetic antenna.

Parameters

- Voltage sources:
  - AC
  - DC + and -
- Defects:
  - Corona
  - moving particle
  - surface discharge
  - floating electrode
- Noises:
  - Random noise
  - CM pulses
  - EM radiation





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6.2.2 HV Validation

				IEC limit	MA/HFCT μ [%]	MA/HFCT σ [%]	EA/HFCT μ [%]	EA/HFCT σ [%]	Syn/HFCT μ [%]	Syn/HFCT σ [%]	MA NPR
Jumping Particle	AC	A4	No Noise	10%	-42	3	-19	3	-27	2	2
			CM pulse	10%	15	47	39	19	30	32	15
		A1	No Noise	10%	-35	8	-45	3	-34	5	2
			CM pulse	10%	25	112	-37	23	-16	37	11
	DC+	A4	No Noise	10%	-25	2	-14	3	-12	2	1
			CM pulse	10%	-18	42	-11	11	-53	33	12
		A1	No Noise	10%	-18	2	-25	2	-13	2	1
			CM pulse	10%	39	52	-16	19	-1	29	11
	DC-	A4	No Noise	10%	-30	2	-12	2	-13	2	1
			CM pulse	10%	-30	18	-11	10	-13	18	10
		A1	No Noise	10%	-16	2	-24	2	-10	2	1
			CM pulse	10%	-17	2	-24	2	-10	2	1
FE	DC-	A1	No Noise	10%	-32	20	-39	18	-29	20	1
		A4	No Noise	10%	-46	23	-36	27	-35	28	2
	AC	A1	No Noise	10%	-22	5	-24	5	-20	5	1
		A4	No Noise	10%	-25	4	-9	4	-8	4	1
Corona	AC	A4	No Noise	66%	-14	55	-6	15	-19	31	11
		A1	No Noise	37%	-27	24	-38	13	-27	18	5
	DC-	A4	No Noise	66%	9	94	-17	21	-29	28	13
		A1	No noise	63%	-24	31	-34	12	-28	19	7
	DC+	A4	No noise	49%	-16	52	-17	16	-21	29	11
		A1	No noise	38%	9	86	-42	17	-32	37	12
SD	AC	A4	No Noise	20%	-34	22	-29	13	-31	14	6
			CM pulse	10%	-71	22	-61	33	-72	25	16
		A1	No Noise	16%	-43	15	-38	11	-37	13	3
			CM pulse	15%	-52	17	-50	25	-56	20	16

The charge estimation is correlated to the signal to noise level.

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Conclusions

- Alternative method for measuring calibrated PD in GIS.
- Its contactless functionality allows its use for online monitoring.
- Allows wave shape construction for defect clustering.
- Calibration method for on-site substations.
- PD charge estimation sensitive to non-impulsive noise, increasing the measurement uncertainty.

Future work

- Noise rejection method to improve the SNR.
- Interference rejection method.

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Thanks for your attention

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Questions?