

MATHMET 2010
International Workshop

Bayesian Approach to assign Consensus Values in PT Comparisons

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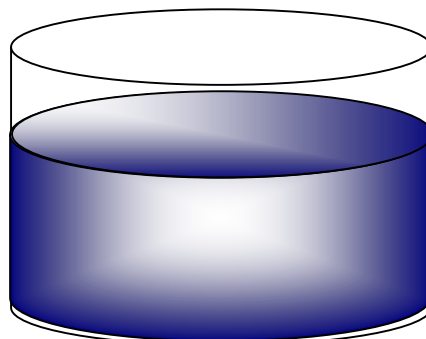
Outline

- **Framework of Proficiency Testing**
 - ✓ PT data
 - ✓ Standardized approach to assign consensus values: NF ISO 13 528
- **The proposed approach: modelling bias**
 - ✓ Methodology
 - ✓ When to introduce latent predictors of bias?
 - ✓ Statistical model
- **Estimating the model**
 - ✓ Bayesian computation of posterior distributions
 - ✓ Getting the consensus value, its associated uncertainty and bias
- **Conclusion**
- **Perspectives**

Framework of the project

- Era-net+ European project entitled « Traceable measurements for biospecies and ion activity in clinical chemistry » (JRP 10, TRACEBIOACTIVITY)
- WP 5: PTB, SP, LNE
- Delivery 2: Evaluating a consensus value in proficiency tests.
- Funded by the European Community's Seventh Framework Programme, ERA-NET Plus, under Grant Agreement No. 217257.

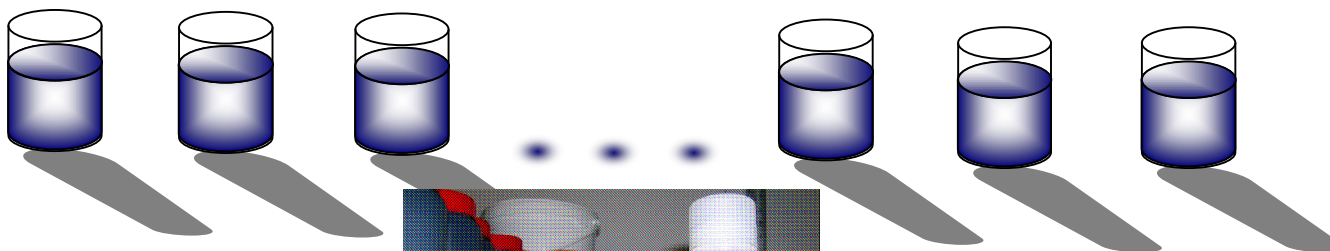
Samples provided by BIPEA



BTEX, PCB, Triazines



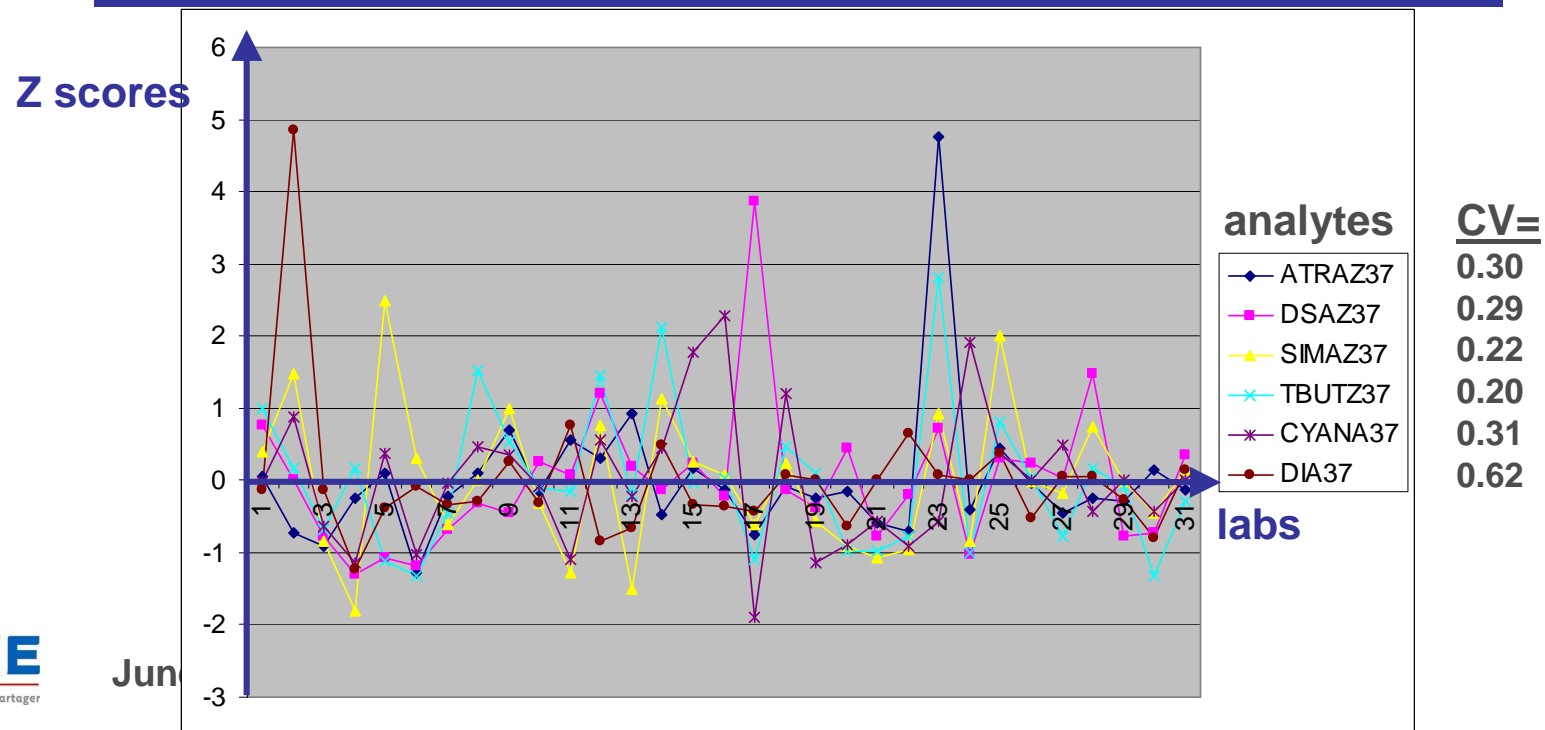
N stable and homogene samples



PT data

- PT provider: BIPEA (2nd provider in Europe)
- Measurands: concentrations of BTEX, Triazine and PCB in water
- No associated uncertainties
- 31 participating laboratories

Example: results for 6 analytes from triazine family



NF ISO 13 528

Statistical methods for use in proficiency testing by interlaboratory comparisons

5.6 Consensus value from participants [see ISO/IEC Guide 43-1:1997, A.1.1 item e)]

5.6.1 General

«With this approach, the assigned value X for the test material used in a round of a proficiency testing scheme is the robust average of the results reported by all the participants in the round, calculated using Algorithm A in Annex C.

Other calculation methods may be used in place of Algorithm A, provided that they have a sound statistical basis and the report describes the method that is used. »

NF ISO 13 528: Algorithm A

Algorithm A to compute robust means and standard deviations

Initialisation

$$x^* = x_i \text{'s median}$$

$$s^* = 1,483 \times \text{median of the } |x_i - x^*|$$

Iterate till convergence

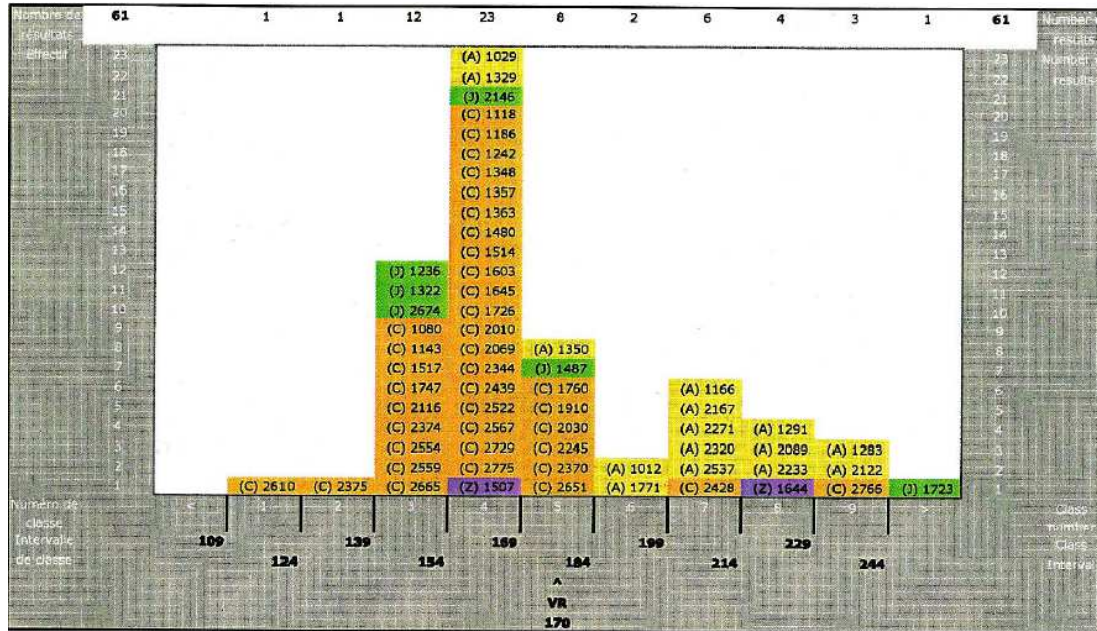
$$x_i^* = \begin{cases} x_i^* - \delta & \text{if } x_i < x^* - \delta \\ x_i^* + \delta & \text{if } x_i > x^* + \delta \\ x_i & \text{otherwise} \end{cases} \quad \delta = 1,5s^*$$

Outputs:

Consensus value: x^* **Bias:** $x_i - x^*$

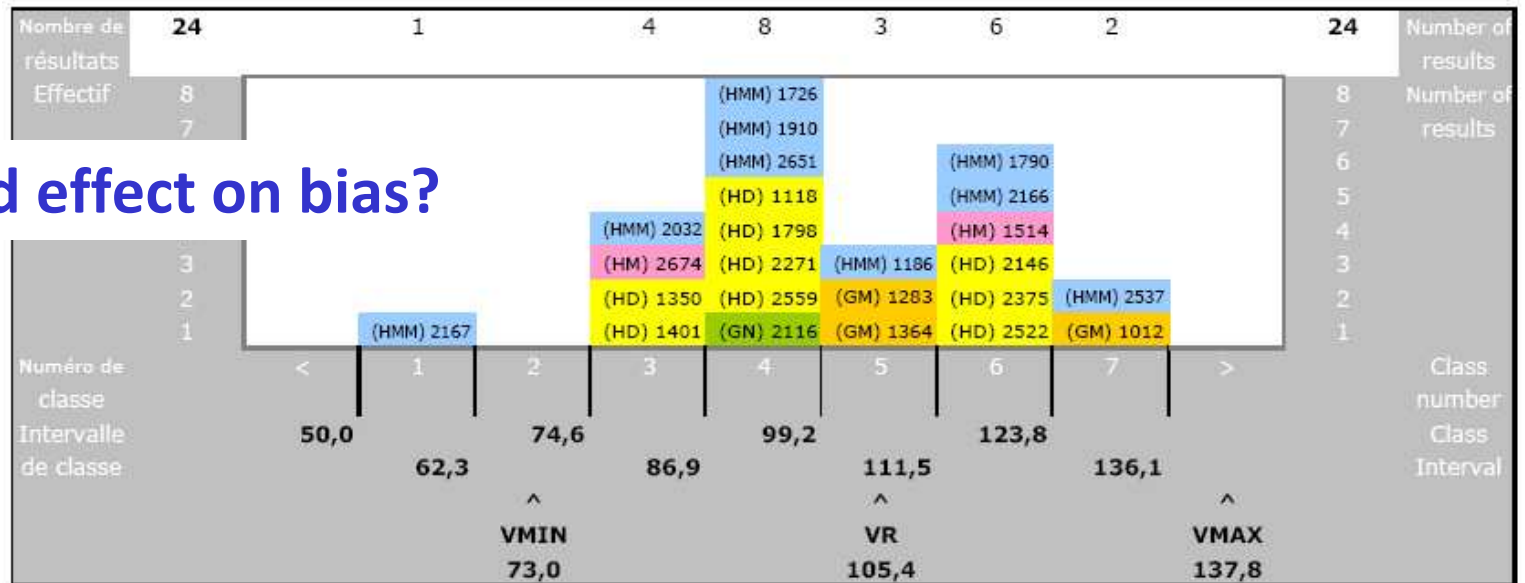
Associated uncertainty: $u_x = 1,25 \times \frac{s^*}{\sqrt{p}}$

Examples

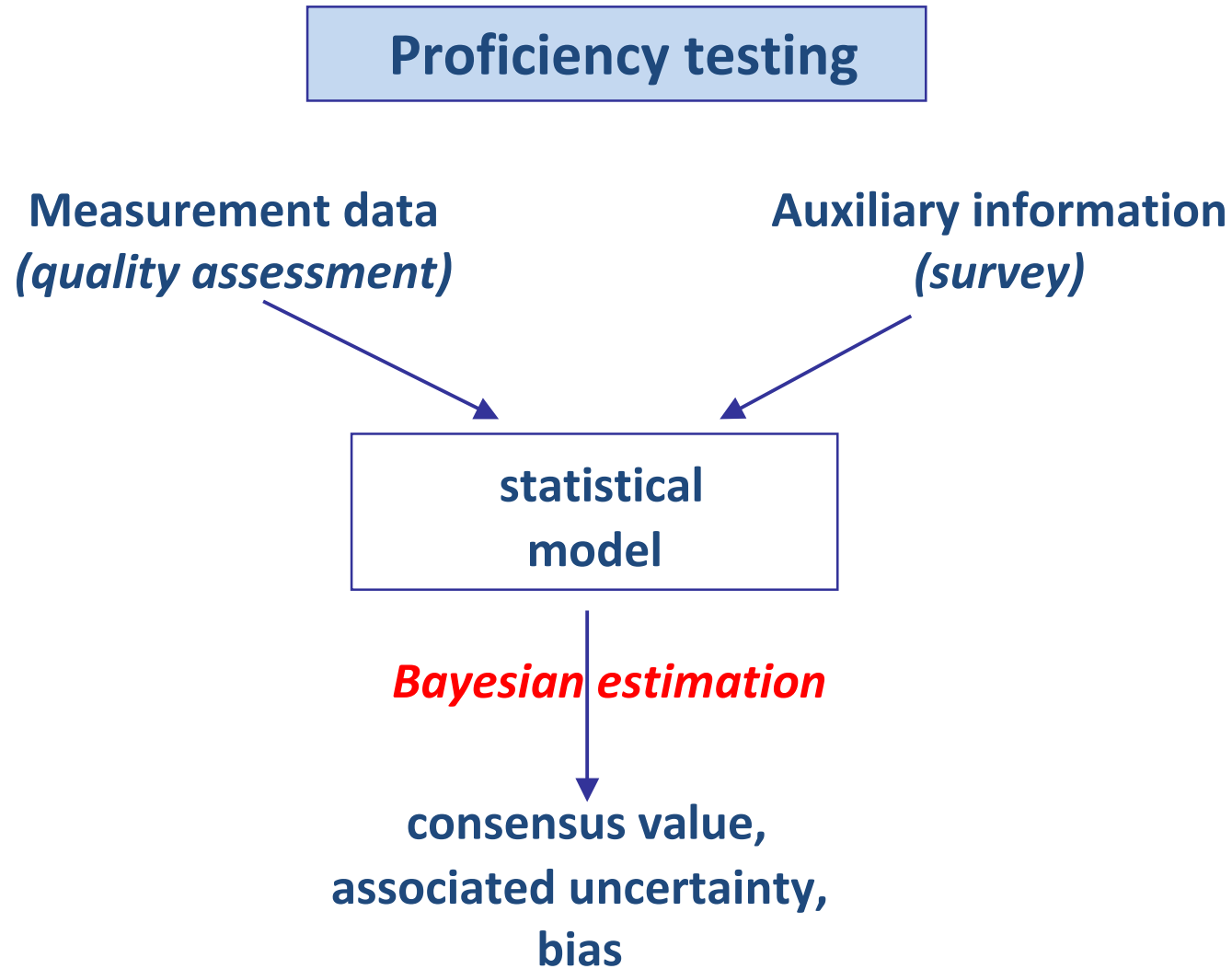


Effect of method on bias?

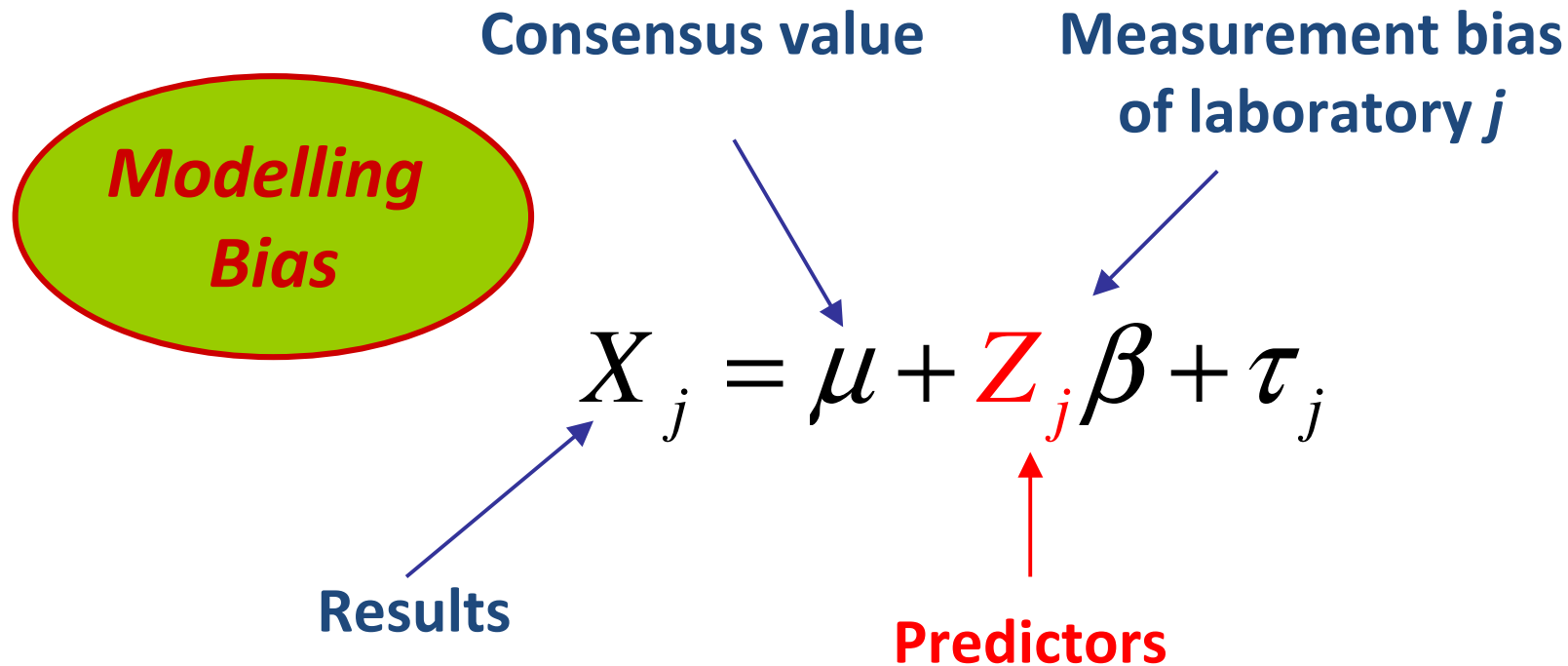
Crossed effect on bias?



Overview



Proposed measurement model



Nature of Z_j ?

Construction of predictors

- Depends on the measurand
- Based on experts knowledge (survey,...)
- **If a few number** of variables can explain bias:
→ Z_j are kept as observed variables

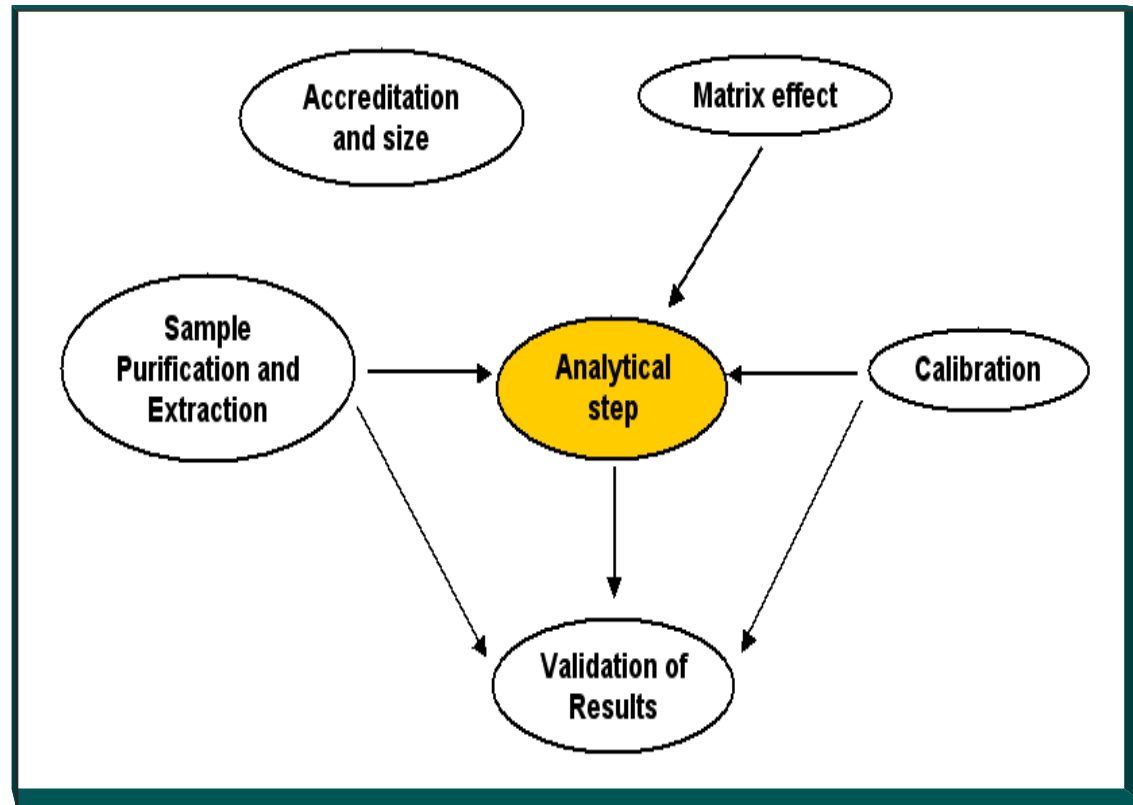
- **If several variables** can explain bias:
→ the observed variables are grouped
→ Z_j are *latent variables* summarizing the observed variables
→ Z_j should capture structures in data

Steps

- Collecting measurements
- Collecting additional information on laboratories (survey)
- Converting this information into variables
→ latent variables
- Constructing a statistical model
- Estimating the model
- Validating the model

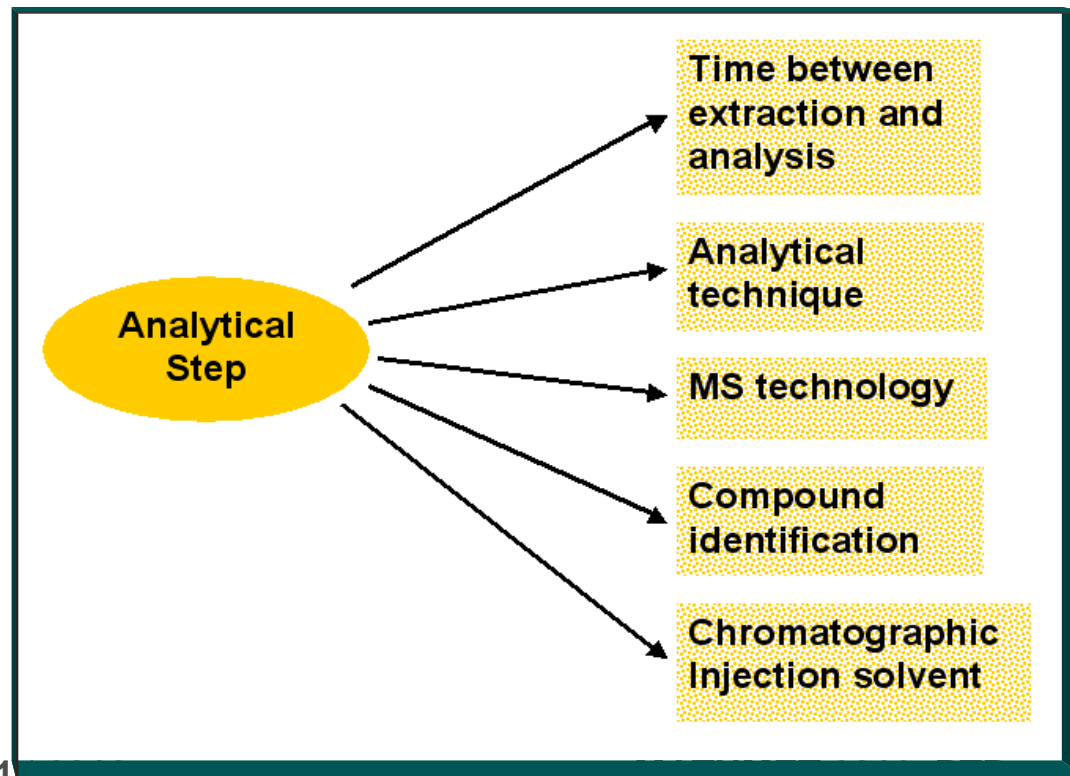
Building latent variables

- Idea: summarizing measurement process + background information on labs
- Blocks = latent (unobserved) concepts, variables

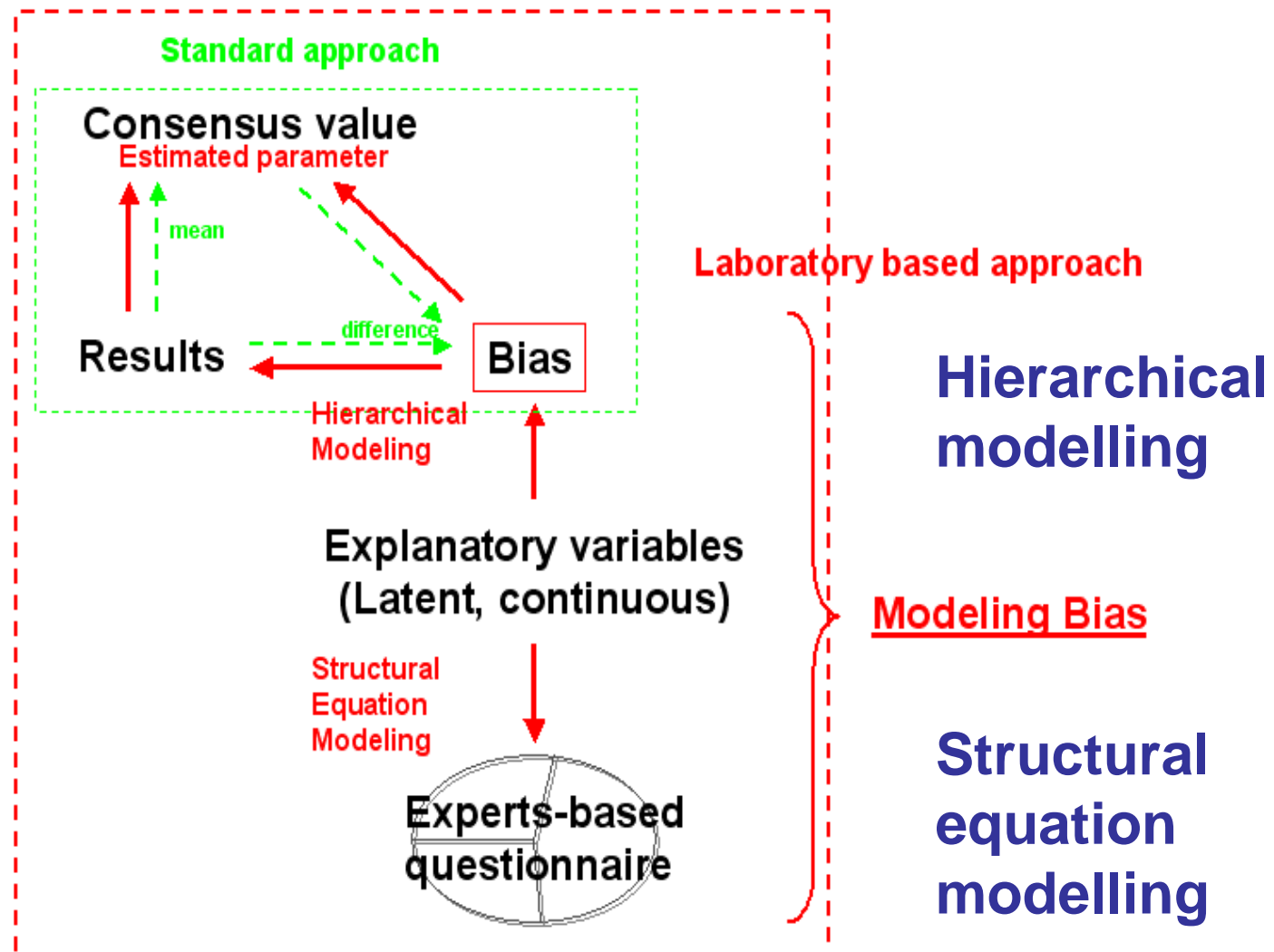


Links between questions and blocks

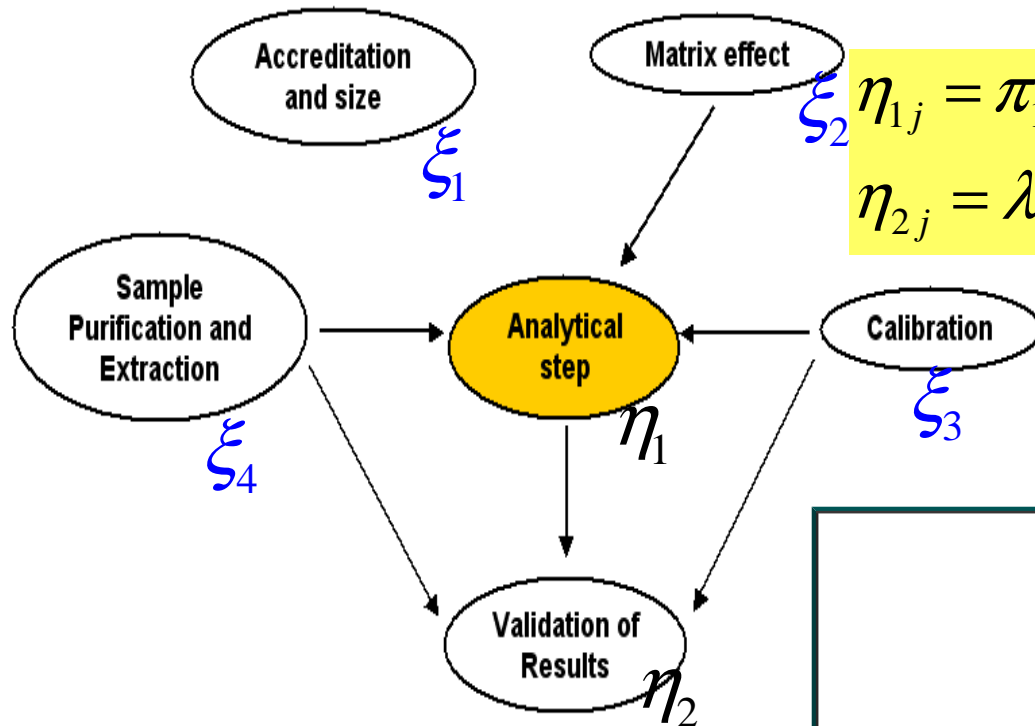
- Latent concepts are measured on observed variables (the questions)
- Example:



Structure of the model



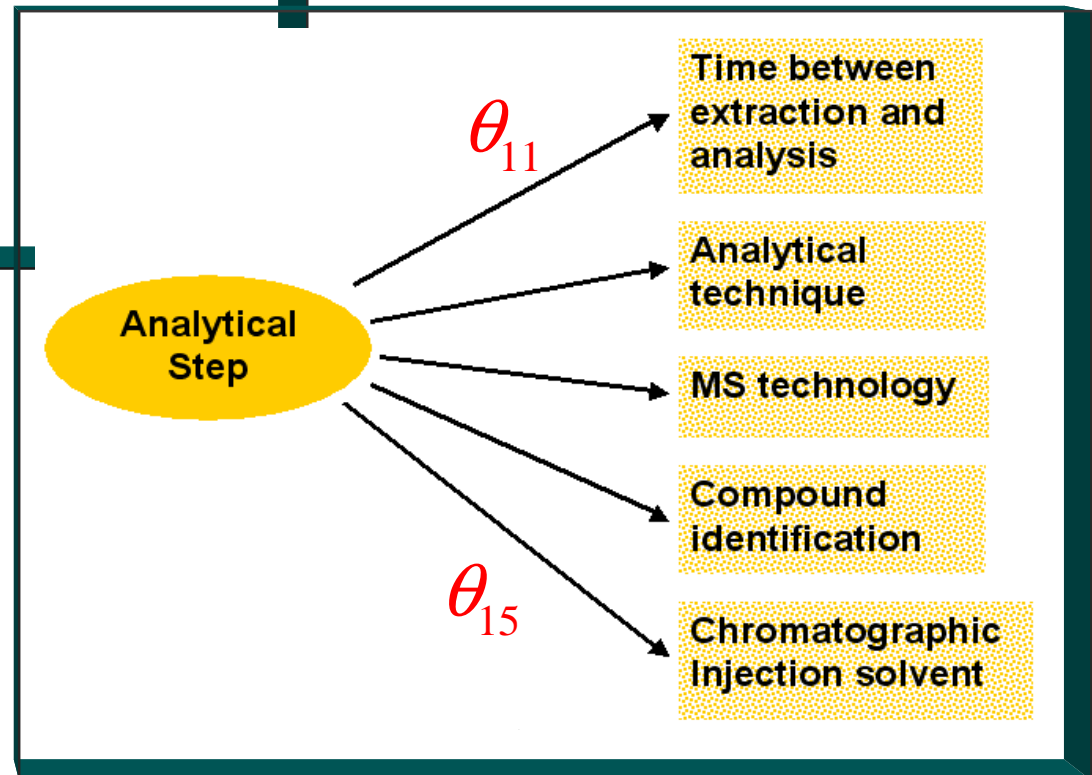
Structural equation modelling



$$\xi_2 \eta_{1j} = \pi_{12} \eta_{2j} + \lambda_{12} \xi_{2j} + \lambda_{13} \xi_{3j} + \lambda_{14} \xi_{4j} + \delta_{1j}$$

$$\eta_{2j} = \lambda_{23} \xi_{3j} + \lambda_{24} \xi_{4j} + \delta_{2j}$$

(Simultaneous equations)

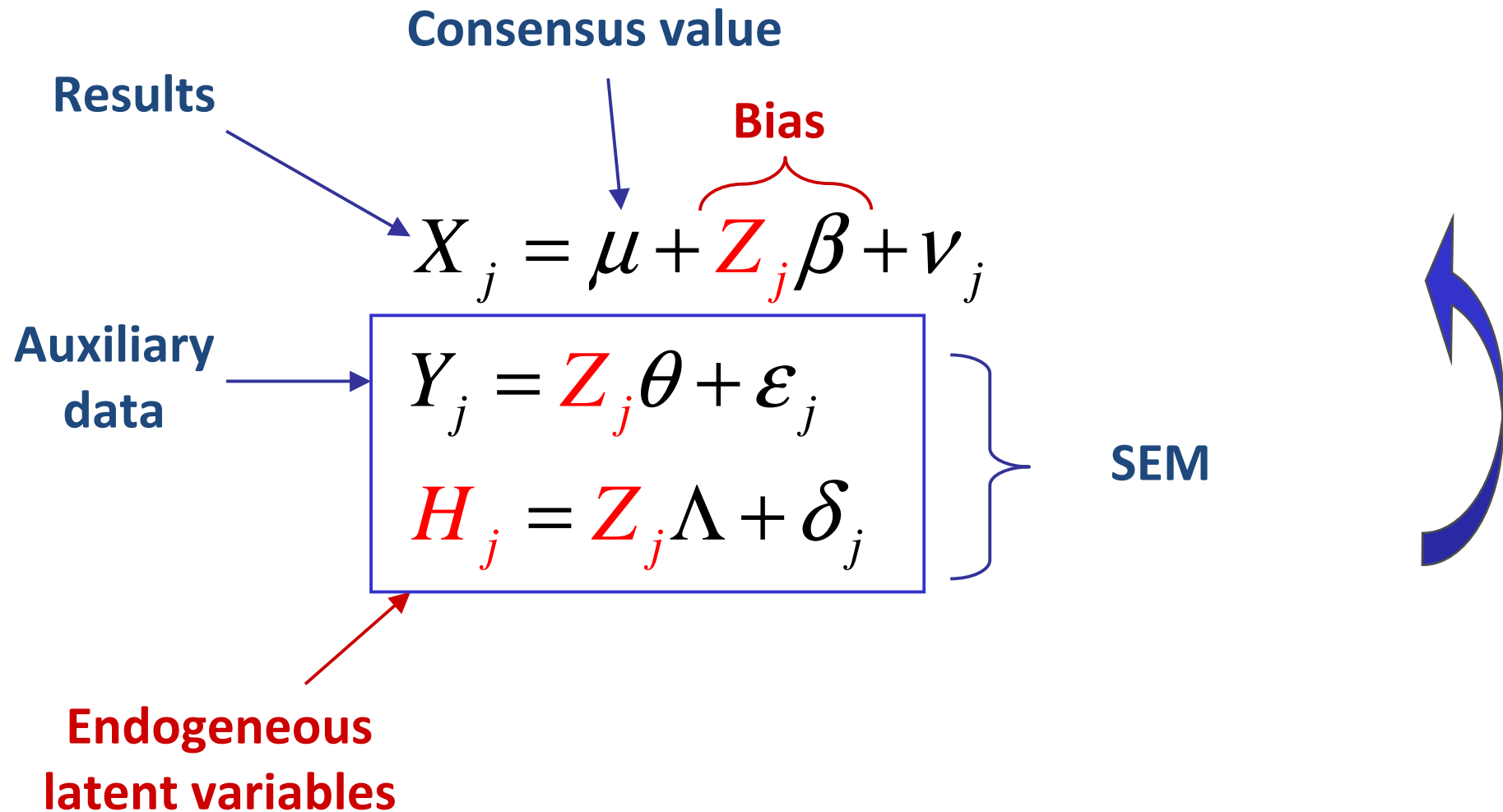


$$y_{1j} = \theta_{11} \eta_{1j} + \varepsilon_{1j}$$

...

$$y_{5j} = \theta_{15} \eta_{1j} + \varepsilon_{5j}$$

Complete model



Model inference: Bayesian approach

- To take into account prior information on parameters (correlations, variances)
- Estimation algorithm based on posterior conditional distributions (MCMC)
- Iterating:
 - ✓ Imputation of latent variables
 - ✓ Posterior sampling of parameters

Proposed Gibbs algorithm to estimate SEM

Initialisation : $\theta^0, \Sigma_{\varepsilon}^0, \Lambda^0, \Sigma_{\delta}^0, \Phi^0$

A l'itération t :

① imputation des variables latentes :

$$Z^t \sim Z | Y, \theta^{t-1}, \Sigma_{\varepsilon}^{t-1}, \Lambda^{t-1}, \Sigma_{\delta}^{t-1}, \Phi^{t-1}$$

② réduction des variables latentes : soit Z^{*t} la VL réduite

$$\textcircled{3} \Sigma_{\varepsilon}^t \sim \Sigma_{\varepsilon} | Y, Z^{*t}, \theta^{t-1}, \Lambda^{t-1}, \Sigma_{\delta}^{t-1}, \Phi^{t-1}$$

$$\textcircled{4} \theta^t \sim \theta | Y, Z^{*t}, \Sigma_{\varepsilon}^t, \Lambda^{t-1}, \Sigma_{\delta}^{t-1}, \Phi^{t-1}$$

$$\textcircled{5} \Sigma_{\delta}^t \sim \Sigma_{\delta} | Y, Z^{*t}, \Lambda^{t-1}, \theta^t, \Sigma_{\varepsilon}^t, \Phi^{t-1}$$

$$\textcircled{6} \Lambda^t \sim \Lambda | Y, Z^{*t}, \Sigma_{\delta}^t, \theta^t, \Sigma_{\varepsilon}^t, \Phi^{t-1}$$

$$\textcircled{7} \Phi^t \sim \Phi | Y, Z^{*t}, \theta^t, \Sigma_{\varepsilon}^t, \Lambda^t, \Sigma_{\delta}^t$$

Imputation of latent variables

Let $\Theta = \{\theta, \Sigma_\varepsilon, \Lambda, \Sigma_\delta, \Phi\}$

$$[Z|Y, \Theta] \propto \prod_{i=1}^n [Z_i|Y_i, \Theta] \propto \prod_{i=1}^n [Y_i|Z_i, \Theta] [Z_i|\Theta]$$

- $[Y_i|Z_i, \Theta] = [Y_i|Z_i, \theta, \Sigma_\varepsilon]$
- $[Z_i|\Theta] = [Z_i|\Lambda, \Sigma_\delta, \Phi] \sim \mathcal{N}(0, \Sigma_Z)$

Results:

$$Z_i|Y_i, \theta, \Sigma_\varepsilon, \Lambda, \Sigma_\delta, \Phi \sim \mathcal{N}(D\theta\Sigma_\varepsilon^{-1}Y_i, D)$$

$$D = \theta\Sigma_\varepsilon^{-1}\theta^t + \Sigma_Z^{-1}.$$

Posterior conditional distributions

Let $\Theta = \{\theta, \Sigma_\varepsilon, \Lambda, \Sigma_\delta, \Phi\}$

$$\begin{aligned} [\Theta|Y, Z] &\propto [Y, Z|\Theta] [\Theta] \\ &\propto [Y|Z, \Theta] [Z|\Theta] [\Theta] \end{aligned}$$

- $[Y|Z, \Theta] = [Y|Z, \theta, \Sigma_\varepsilon]$
- $[Z|\Theta] = [Z|\Lambda, \Sigma_\delta, \Phi] = [H|\Xi, \Lambda, \Sigma_\delta] [\Xi|\Phi]$
- $[\Theta] = [\theta, \Sigma_\varepsilon] [\Lambda, \Sigma_\delta] [\Phi]$

$$[\Theta|Y, Z] \propto \underbrace{[Y|Z, \theta, \Sigma_\varepsilon] [\theta, \Sigma_\varepsilon]}_{[\theta, \Sigma_\varepsilon|Y, Z]} \underbrace{[H|\Xi, \Lambda, \Sigma_\delta] [\Lambda, \Sigma_\delta]}_{[\Lambda, \Sigma_\delta|Y, Z]} \underbrace{[\Xi|\Phi] [\Phi]}_{[\Phi|Z]}$$

Posterior conditional distributions

Conjugate models
Normal/Gamma

$$Y_k = \theta_k Z + \varepsilon_k, \quad Y_k \sim N(\theta_k Z, \Sigma_\varepsilon)$$

$$\theta_k | Y, Z, \Sigma_\varepsilon \sim \mathcal{N}(D_k A_k, \Sigma_{\varepsilon k} D_k)$$

$$D_k = (Z^t Z + \Sigma_{0\varepsilon}^{-1})^{-1}$$

$$A_k = Z^t Y_k + \Sigma_{0\varepsilon}^{-1} \theta_{0k}$$

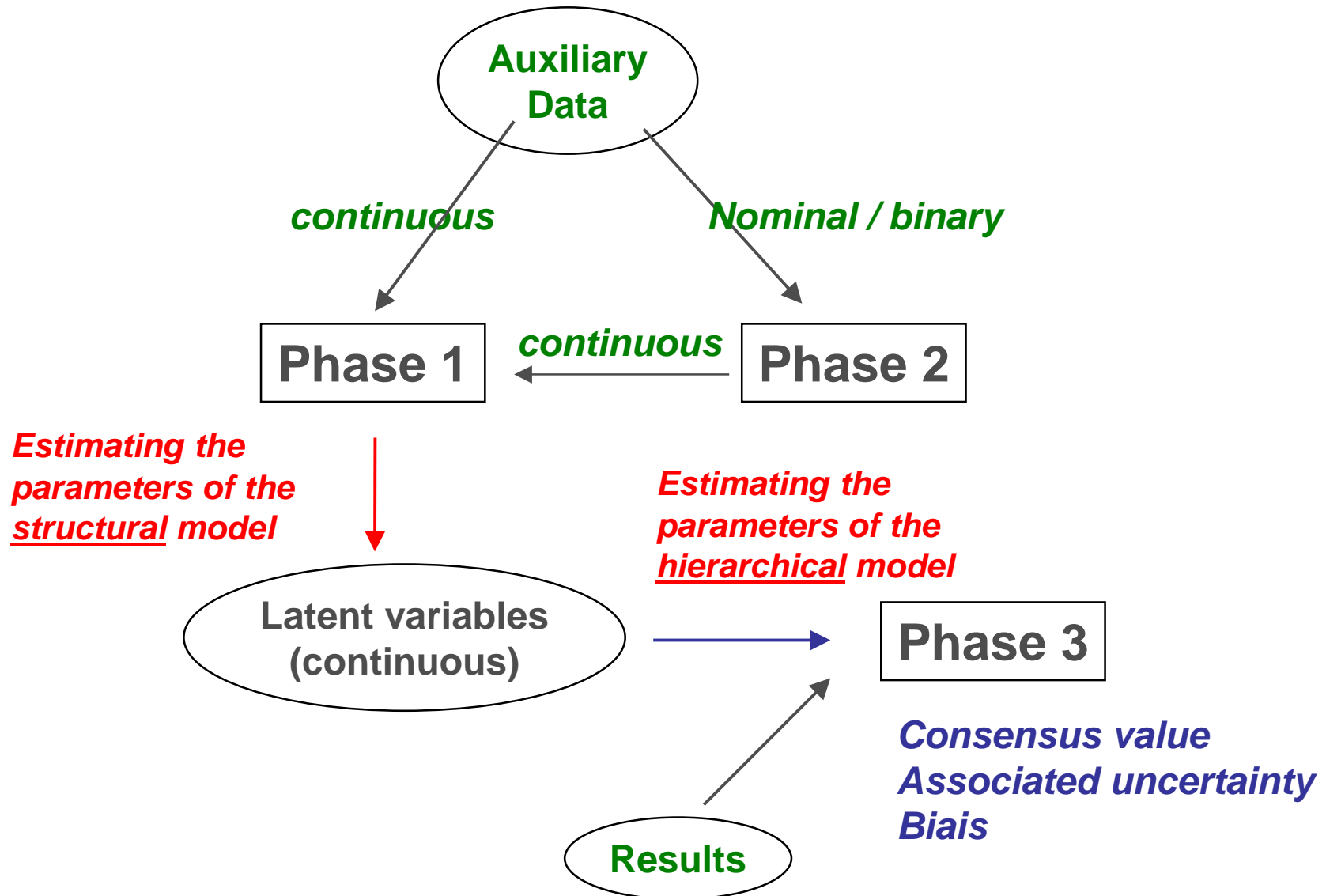
$$H_k = \Lambda_k Z_k + \delta_k, \quad H_k \sim N(\Lambda_k Z_k, \Sigma_{\delta k})$$

$$\Lambda_k | Z, \Sigma_{\delta k} \sim \mathcal{N}(D_k A_k, \Sigma_{\delta k} D_k)$$

$$D_k = (Z^t Z + \Sigma_{0\delta}^{-1})^{-1}$$

$$A_k = Z^t H_k + \Sigma_{0\delta}^{-1} \Lambda_{0k}$$

Estimation of the model: 3 phases



Conclusion

- **New approach to compute consensus values and their associated uncertainties**
 - ✓ **Modelling bias**
 - ✓ **Modelling structures in auxiliary data**
- **To propose different models from ANOVA to SEM to handle structures in the auxiliary information.**
- **Collaborative work between experts and statisticians.**
- **Model inference in progress for nominal auxiliary data.**

Perspectives

- To test the approach with SEM on water pollutants when the statistical tool works with nominal data
- To adapt the model for creatinine data (another structure of the auxiliary information)